

Recent Developments in StarPU

IPL C2S@Exa – Pole 3

Olivier Aumage – Runtime Team Inria – LaBRI

Bordeaux, July 10-11, 2014

Heterogeneous Parallel Platforms

Heterogeneous Association

- General purpose processor
- Specialized accelerator

Generalization

- Combination of various units
 - Latency-optimized cores
 - Throughput-optimized cores
 - Energy-optimized cores
- Distributed cores
 - Standalone GPUs
 - Intel Xeon Phi (MIC)
 - Intel Single-Chip Cloud (SCC)
- Integrated cores
 - Intel Haswell
 - AMD Fusion
 - nVidia Tegra





Programming Models for Heterogeneous Platforms?

How to Program these architectures?

- Multicore programming
 - pthreads, OpenMP, TBB, ...
- Accelerator programming
 - Consensus on OpenCL?
 - (Often) Pure offloading model
- Hybrid models?
 - Take advantage of all resources
 - Complex interactions



StarPU Programming Model: Sequential Task Flow

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StarPU Programming Model: Sequential Task Flow

- Express parallelism...
- ... using the natural program flow
- Submit tasks in the sequential flow of the program...
- ... then let the runtime schedule the tasks asynchronously

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Ex.: Sequential Cholesky Decomposition

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Kernel tasks submitted asynchronously









- Kernel tasks submitted asynchronously
- Data dependences determined implicitely









- Kernel tasks submitted asynchronously
- Data dependences determined implicitely
- A graph of tasks is built









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A graph of tasks is built

Kernel tasks submitted asynchronously

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- Kernel tasks submitted asynchronously
- Data dependences determined implicitely
- A graph of tasks is built
- The graph of tasks is executed







StarPU Execution Model: Task Scheduling

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StarPU Execution Model: Task Scheduling

Mapping the graph of tasks (DAG) on the hardware

- Allocating computing resources
- Enforcing dependency constraints
- Handling data transfers

Adaptiveness

- A single DAG enables multiple schedulings
- A single DAG can be mapped on multiple platforms



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University of Tennessee, INRIA HiePACS, INRIA Runtime

QR decomposition on 16 CPUs (AMD) + 4 GPUs (C1060)



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QR kernel properties

Kernel SGEQRT							
CPU:	9 GFlop/s	GPU:	30 GFlop/s	Speed-up:	3		
Kernel STSQRT							
CPU:	12 GFlop/s	GPU:	37 GFlop/s	Speed-up:	3		
Kernel SOMQRT							
CPU:	8.5 GFlop/s	GPU:	227 GFlop/s	Speed-up:	27		
Kernel SSSMQ							
CPU:	10 GFlop/s	GPU:	285 GFlop/s	Speed-up:	28		

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Consequences

- Task distribution
 - SGEQRT: 20% Tasks on GPU
 - SSSMQ: 92% tasks on GPU

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Consequences

- Task distribution
 - SGEQRT: 20% Tasks on GPU
 - SSSMQ: 92% tasks on GPU
- Taking advantage of heterogeneity!
 - Only do what you are good for
 - Don't do what you are not good for



StarPU in a Nutshell

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StarPU in a Nutshell

Rationale

- Implement the sequential task flow programming model
- Map computations on heterogeneous computing units

Programming Model

- Task
- Data
- Relationships
 - Task \leftrightarrow Task
 - $\ \text{Task} \leftrightarrow \text{Data}$

Runtime System

- Heterogeneous Task scheduling
- Application Programming Interface (Library)

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Recent Developments

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Recent Developments

Platform Support

- Distributed Computing: StarPU-MPI
 - ADT MORSE: MAGMA support and tests TGCC Curie (Florent Pruvost's Talk)
- Out-of-core support
- Intel MIC / Xeon Phi support
- SimGrid support
 - ANR SONGS

Programming Support

- OpenMP 4.0 compiler: Klang-OMP
 - ADT K'Star (cf Philippe Virouleau's Talk)
- OpenCL backend

Scheduling Support

- Composition on multi and many cores
 - Scheduling contexts
- Modular schedulers



Platform Support

- Distributed Computing
- Out-of-core
- Many-cores
- Simulation

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Sequential Task Flow Paradigm on Clusters

Task \leftrightarrow Node Mapping

- Provided by the application
- Can be altered dynamically

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Sequential Task Flow Paradigm on Clusters

 $\mathsf{Task} \leftrightarrow \mathsf{Node} \ \mathsf{Mapping}$

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Sequential Task Flow Paradigm on Clusters

 $\mathsf{Task} \leftrightarrow \mathsf{Node} \ \mathsf{Mapping}$

- Provided by the application
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Communications

- Inferred from the task graph
 - Dependencies
- Automatic Isend and Irecv calls





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Communication Requests



Summary: Interoperability between StarPU and MPI

- On-going work
- Ph.D thesis Marc Sergent (with CEA CESTA)

Related Works

- MAGMA-MORSE library port on top of StarPU-MPI
- ADT MORSE, cf Florent Pruvost's talk
- ANR SOLHAR (Abdou Guermouche)
- DGA RAPID Hi-BOX (Airbus)

Out-of-Core

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Out-of-Core

Integration with general StarPU's memory management layer

- StarPU data handles
- Task dependencies

Multiple disk drivers supported

- Legacy stdio/unistd methods
- Google's LevelDB
 - (key/value database library)

On-going internship



Support for Manycore Accelerators

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Support for Manycore Accelerators

Manycores

- Intel xeon phi (MIC)
- Also: Intel SCC (Single-Chip Cloud)

Technical details

- Support shared for common characteristics
- Several StarPU instances
 - One CPU instance (the source)
 - One instance per manycore accelerator (the sink)
 - Scheduling performed by the main CPU StarPU instance
- Separate compilation for CPU code and MIC code
- Straightforward port

Simulation with SimGrid

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Simulation with SimGrid

Scheduling without executing kernels

- Requires the SimGrid simulation environment
- Enables simulating large-scale scenarios
 - Large data sets
 - Large simulated hardware plaform
- Relies on real performance models...
- ... collected by StarPU on a real machine
- Enables fast experiments when designing application algorithms
- Enables fast experiments when designing scheduling algorithms

ANR Songs Partnership



Histograms for state distribution

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Progamming Support

- OpenMP 4.0
- OpenCL

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High-Level StarPU Programming – OpenMP 4.0 Compiler

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High-Level StarPU Programming – OpenMP 4.0 Compiler

Compiler Klang-omp

- OpenMP 4.0 Compiler: on-going work with MOAIS Team
 - ADT K'Star
 - Philippe Virouleau, MOAIS (Friday's talk)
 - Pierrick Brunet (IJD/junior engineer), MOAIS
- IJD Runtime, 1-year, 2014-2015
 - Porting applications on top of OpenMP 4.0
 - ScalFMM

Technical details

- LLVM-based compiler
- Builds on open source Intel compiler clang-omp
- Good support for homogeneous OpenMP features
 - Dependent tasks
- Heterogeneous features: on-going work
- Benchmark suite: KaStors



High-Level StarPU Programming – StarPU/OpenCL

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High-Level StarPU Programming – StarPU/OpenCL

SOCL Rationale

- Run generic OpenCL codes...
- ... on top of StarPU
- Technical details
 - StarPU as an OpenCL backend
 - ICD: Installable Client Driver
 - Redirects OpenCL calls...
 -to StarPU routines

Kernels

SOCL can itself use OpenCL Kernels



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Scheduling Support

- Composition
- Modular schedulers

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Composition: Scheduling contexts

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Composition: Scheduling contexts

Rationale

- Sharing computing resources...
- ... among multiple DAGs
- ... simultaneously
- Composing codes, kernels

Scheduling contexts

- Map DAGs on subsets of computing units
- Isolate competing kernels or library calls
 - OpenMP kernel, Intel MKL, etc.
- Select scheduling policy per context

Ph.D thesis Andra Hugo





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Components: C2S@Exa Ph.D Proposal

Topic

- Software component model with task scheduling
- ... for many-core based parallel architectures
- ... applied to the Gysela5D code

Participants

- Team Avalon, Christian Perez
- Maison de la Simulation, Julien Bigot
- CEA Cadarache, Guillaume Latu
- Team Runtime, Olivier Aumage

Modular Schedulers

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Modular Schedulers

Ph.D thesis Marc Sergent

Scheduling zones

- Delimited by accumulation basins
- One "pump" per scheduling zone

Building new schedulers

- Simple, well defined properties
- Assembly rules
- Reusable pieces
 - Queue management



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Thanks for your attention. Do you have any questions?

StarPU

Web Site: http://runtime.bordeaux.inria.fr/starpu/ SVN Repository: http://gforge.inria.fr/projects/starpu/ LGPL License

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