

Univ. Côte d'Azur and Inria, France



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# **Geometric Statistics**

Mathematical foundations and applications in computational anatomy



Freely adapted from "Women teaching geometry", in Adelard of Bath translation of Euclid's elements, 1310.

5/ Advanced Stats: empirical estimation and generalized PCA

Ecole d'été de Peyresq, Jul 1-5 2019







Geometric Statistics: Mathematical foundations and applications in computational anatomy

Intrinsic Statistics on Riemannian Manifolds Manifold-Valued Image Processing Metric and Affine Geometric Settings for Lie Groups Parallel Transport to Analyze Longitudinal Deformations

### **Advances Statistics: CLT & PCA**

- Estimation of the empirical Fréchet mean & CLT
- Principal component analysis in manifolds
- Natural subspaces in manifolds: barycentric subspaces
- Rephrasing PCA with flags of subspaces

# Several definitions of the mean Tensor moments of a random point on M

□  $\mathfrak{M}_1(x) = \int_M \overline{xz} \, dP(z)$  Tangent mean: (0,1) tensor field □  $\mathfrak{M}_2(x) = \int_M \overline{xz} \otimes \overline{xz} \, dP(z)$  Covariance: (0,2) tensor field □  $\mathfrak{M}_k(x) = \int_M \overline{xz} \otimes \overline{xz} \otimes \cdots \otimes \overline{xz} \, dP(z)$  k-contravariant tensor field □  $\sigma^2(x) = Tr_g(\mathfrak{M}_2(x)) = \int_M dist^2(x, z) \, dP(z)$  Variance function

#### Mean value = optimum of the variance

- □ **Frechet mean** [1944] = (global) minima of p-variance (includes median)
- □ Karcher mean [1977] = local minima
- **Exponential barycenters** = critical points (P(C) = 0)  $\overline{D}$

$$\mathfrak{M}_1(\overline{x}) = \int_M \overline{\overline{x}z} dP(z) = 0$$
 (implicit definition)

#### **Covariance at the mean**

$$\square \mathfrak{M}_2(\bar{x}) = \int_M \overline{\bar{x}z} \otimes \overline{\bar{x}z} \, dP(z)$$

xy 🔊

 $T_{\bar{\mathbf{x}}} S_{2}$ 

# Algorithms to compute the mean

## Karcher flow (gradient descent)

$$\bar{x}_{t+1} = \exp_{\bar{x}_t}(\epsilon_t v_t) \text{ with } v_t = E(\overline{y}\overline{x}) = \frac{1}{n} \sum_i \log_{\bar{x}_t}(x_i)$$

□ Usual algorithm with  $\epsilon_t = 1$  can diverge on SPD matrices [Bini & Iannazzo, Linear Algebra Appl., 438:4, 2013]

 Convergence for non-negative curvature (p-means) [Afsari, Tron and Vidal, SICON 2013]

#### Inductive / incremental weighted means

$$\Box \ \bar{x}_{k+1} = \exp_{\bar{x}_k} \left( \frac{1}{k} \ v_k \right) \ with \ v_k = \log_{\bar{x}_k} (x_{k+1})$$

 On negatively curved spaces [Sturm 2003], BHV centroid [Billera, Holmes, Vogtmann, 2001]

□ On non-positive spaces [G. Cheng, J. Ho, H. Salehian, B. C. Vemuri 2016]

# Stochastic algorithm

- □ [Bonnabel IEE TAC 58(9) 2013]
- □ [Arnaudon & Miclo, Stoch. Proc. & App. 124, 2014]

# Asymptotic behavior of the mean

#### Uniqueness of p-means with convex support

[Karcher 77 / Buser & Karcher 1981 / Kendall 90 / Afsari 10 / Le 11]

- Non-positively curved metric spaces (Aleksandrov): OK [Gromov, Sturm]
- Positive curvature: [Karcher 77 & Kendall 89] concentration conditions: Support in a regular geodesic ball of radius  $r < r^* = \frac{1}{2} \min(inj(M), \pi/\sqrt{\kappa})$

# Bhattacharya-Patrangenaru CLT [BP 2005, B&B 2008]

□ Under suitable concentration conditions, for IID n-samples:

- $\bar{x}_n \rightarrow \bar{x}$  (consistency of empirical mean)
- $\sqrt{n} \log_{\bar{x}}(\bar{x}_n) \rightarrow N(0, \bar{H}^{-1} \Sigma \bar{H}^{-1})$  if  $\bar{H} = \int_M Hess_{\bar{x}}(d^2(y, \bar{x})) \mu(dy)$  invertible

## Questions

- □ Intelligible expression of Hessian?
- □ What happens for a small sample size (non-asymptotic behavior)?
- □ Can we extend results to affine connection spaces?

# **Concentration assumptions**

 $\square$  Uniqueness of the mean, support of diameter <  $\varepsilon$ 

# Riemannian manifold: Karcher & Kendall Concentr. Cond.

- □ Supp( $\mu$ ) ⊂ B(x,r) with r <  $\frac{1}{2}$  inj(x)
- $\Box \quad \sup_{x \in B(x,r)} \kappa(x) < \pi^2/(4r)^2$

#### Affine connection spaces: Arnaudon & Li convexity cond.

- $\square \ \rho: M \times M \ \rightarrow R^+ \text{ separating function}$ 
  - Separability:  $\rho(x, y) = 0 \Leftrightarrow x = y$
  - Convexity along geodesic:  $\rho(\gamma_1(t), \gamma_2(t)): R \to R^+ \ convex$
- □ p-convex geometry:  $c \operatorname{dist}^p(x, y) \le \rho(x, y) \le C \operatorname{dist}^p(x, y)$
- Uniqueness of exponential barycenter (compact support)

# **Taylor expansion in manifolds**

#### The mean is an exponential barycenter

- □ Tangent mean field:  $\mathfrak{M}_1(x) = \int_M \log_x(z) \mu(dz)$ has a zero at  $\bar{x}$ . Problem: vector field
- □ Recentered man field is a mapping of vector spaces  $N_x(v) = \prod_{x_v}^x \mathfrak{M}_1(\exp_x(v)) = \int_M \prod_{x_v}^x \log_{x_v}(y) \mu(dy)$

has a zero at  $\bar{v} = \log_x(\bar{x})$ 

#### Neighboring log expansion (derived from Gavrilov)



# Non-Asymptotic behavior of empirical means

### Moments of the Fréchet mean of a n-sample

- Taylor expansions based on [Gavrilov 2007]
- □ Unexpected bias in 1/n on empirical mean (gradient of curvature-cov.) bias( $\bar{x}_n$ ) =  $E(log_{\bar{x}}(\bar{x}_n)) = \frac{1}{6n} (\mathfrak{M}_2: \nabla R: \mathfrak{M}_2) + O(\epsilon^5, 1/n^2)$
- Concentration rate modulated by the curvature-covariance:

 $Cov(\bar{x}_n) = E\left(\log_{\bar{x}}(\bar{x}_n) \otimes \log_{\bar{x}}(\bar{x}_n)\right) = \frac{1}{n}\mathfrak{M}_2 + \frac{1}{3n}\mathfrak{M}_2: \mathbb{R}:\mathfrak{M}_2 + O(\epsilon^5, 1/n^2)$ 

- Asymptotically infinitely fast CV for negative curvature
- No convergence (LLN fails) at the limit of KKC condition

#### [XP, Curvature effects on the empirical mean in Manifolds 2019, arXiv:1906.07418]

# **Constant curvature spaces**

□ Symmetric spaces: no bias

□ Variance is modulated w.r.t. Euclidean:  $Var(\bar{x}_n) = \alpha \frac{\sigma^2}{n}$ 

**High concentration expansion** 

$$\Box \ \alpha = 1 + \frac{2}{3} \left( 1 - \frac{1}{d} \right) \left( 1 - \frac{1}{n} \right) \kappa \sigma^2 + O(\epsilon^5)$$

**Asymptotic CLT expansion** 

$$\Box \ \alpha = \left(\frac{1}{d} + \left(1 - \frac{1}{d}\right)\overline{h}\right)^{-2} + O(n^{-2})$$

# **Archetypal modulation factor**

□ Uniform distrib on  $S(\bar{x}, \theta) \subset M$ large n, large d

$$\Box \ \alpha = \frac{\tan^2(\sqrt{\kappa\theta^2})}{\kappa\theta^2}$$









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Convergence rate modulation factor, hyperbolic space, space dim=3, N > 5



# **Conclusions**

#### High concertation expansion very accurate for low theta

#### Asymptotic expansion very accurate for n> 10

## Main variable controlling the modulation is variancecurvature tensor

 $R(\blacksquare, \circ) \blacksquare: \mathfrak{M}_2$ 

# Main variable controling the bias $\mathfrak{M}_2: \nabla R(^\circ, \blacksquare) \blacksquare: \mathfrak{M}_2$

# Trimester on Statistics with Geometry and Topology

## Geometric Statistics workshop Toulouse, 30-08/05-09 2019

- □ Fri 30-08 PM: Susan Holmes (mini-course 1)
- □ Mon 02-09 AM: Susan Holmes (mini-course 2)

PM: Ezra Miller (Sampling from stratified spaces. 1: Stratified spaces)

- Tue 03-09 AM: Ezra Miller (Sampling from stratified spaces. 2: Fréchet means)
   PM: Stephan Huckeman (TBA) / Thomas Hotz (Universal, nonasymptotic confidence sets for extrinsic and intrinsic means)
- Wed 04-09 AM: Xavier Pennec (Statistics on Riemannian manifolds and affine connection spaces. 1: manifolds and basic statistics)
   PM: Huiling Le (Empirical Likelihood of Frechet Means) / Alice Le Brigant (TBA)
- Thu 05-09 AM: Xavier Pennec (Statistics on Riemannian manifolds and affine connection spaces. 2: Barycentric subspace analysis, asymptotic and non-asymptotic behavior of the empirical mean)
  - PM: Nina Miolane & TBA

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# Low dimensional subspace approximation?



Manifold of cerebral ventricles Etyngier, Keriven, Segonne 2007.



Manifold of brain images S. Gerber et al, Medical Image analysis, 2009.

- $\hfill\square$  Beyond the 0-dim mean  $\rightarrow$  higher dimensional subspaces
- When embedding structure is already manifold (e.g. Riemannian):
   Not manifold learning (LLE, Isomap,...) but submanifold learning
- Natural subspaces for extending PCA to manifolds?

# Tangent PCA (tPCA)

# Maximize the squared distance to the mean (explained variance)

- a Algorithm
  - Unfold data on tangent space at the mean
  - Diagonalize covariance at the mean  $\Sigma(x) \propto \sum_i \overline{\bar{x}x_i} \, \overline{\bar{x}x_i}^t$
- □ Generative model:
  - Gaussian (large variance) in the horizontal subspace
  - Gaussian (small variance) in the vertical space

 $\square$  Find the subspace of  $T_{\chi}M$  that best explains the variance

# **Problems of tPCA**

## Analysis is done relative to the mean

□ What if the mean is a poor description of the data?

- Multimodal distributions
- Uniform distribution on subspaces
- Large variance w.r.t curvature







Bimodal distribution on S2

Images courtesy of S. Sommer

### Principal Geodesic / Geodesic Principal Component Analysis

# Minimize the squared Riemannian distance to a low dimensional subspace (unexplained variance)

 $\Box \text{ Geodesic Subspace: } GS(x, w_1, \dots, w_k) = \{ \exp_x(\sum_i \alpha_i w_i) \text{ for } \alpha \in \mathbb{R}^k \}$ 

- Parametric subspace spanned by geodesic rays from point x
- Beware: GS have to be restricted to be well posed [XP, AoS 2018]
  PGA (Fletcher et al., 2004, Sommer 2014)

□ Geodesic PCA (GPCA, Huckeman et al., 2010)

- □ Generative model:
  - Unknown (uniform ?) distribution within the subspace
  - Gaussian distribution in the vertical space

### Asymmetry w.r.t. the base point in $GS(x, w_1, ..., w_k)$

Totally geodesic at x only

# **Patching the Problems of tPCA / PGA** Improve the flexibity of the geodesics

- 1D regression with higher order splines [Gu, Machado, Leite, Vialard, Singh, Niethammer, Absil,...]
  - Control of dimensionality for n-D Polynomials on manifolds?

#### Iterated Frame Bundle Development [HCA, Sommer GSI 2013]

- Iterated construction of subspaces
- Parallel transport in frame bundle
  - Intrinsic asymmetry between components

#### **Nested "algebraic" subspaces**

- Principal nested spheres [Jung, Dryden, Marron 2012]
- □ Quotient of Lie group action [Huckemann, Hotz, Munk, 2010]

# • No general semi-direct product space structure in general Riemannian manifolds



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# Affine span in Euclidean spaces

## Affine span of (k+1) points: weighted barycentric equation

Aff
$$(x_0, x_1, \dots x_k) = \{x = \sum_i \lambda_i x_i \text{ with } \sum_i \lambda_i = 1\}$$
  
=  $\{x \in \mathbb{R}^n \text{ s. } t \sum_i \lambda_i (x_i - x) = 0, \lambda \in \mathbb{P}_k^*\}$ 

#### Key ideas:

Triangulate from several reference:
 locus of weighted means



# Barycentric subspaces and Affine span in Riemannian manifolds

## Fréchet / Karcher barycentric subspaces (KBS / FBS)

□ Normalized weighted variance:  $\sigma^2(\mathbf{x},\lambda) = \sum \lambda_i dist^2(x,x_i) / \sum \lambda_i$ □ Set of absolute / local minima of the  $\lambda$ -variance □ Works in stratified spaces (may go accross different strata)

• Non-negative weights: Locus of Fréchet Mean [Weyenberg, Nye]

#### **Exponential barycentric subspace and affine span**

- □ Weighted exponential barycenters:  $\mathfrak{M}_1(x, \lambda) = \sum_i \lambda_i \overrightarrow{xx_i} = 0$
- $\Box \ \mathsf{EBS}(x_0, \dots x_k) = \{ x \in M^*(x_0, \dots x_k) \mid \mathfrak{M}_1(x, \lambda) = 0 \}$
- □ Affine span = closure of EBS in M  $Aff(x_0, ..., x_k) = \overline{EBS(x_0, ..., x_k)}$

#### Questions

- Local structure: local manifold? dimension? stratification?
- $\square$  Relationship between KBS  $\subset$  FBS, EBS and affine span?

[X.P. Barycentric Subspace Analysis on Manifolds. Annals of statistics. 2018. To appear. arXiv:1607.02833]

# Analysis of Barycentric Subspaces

# **Assumptions:**

□ Restrict to the **punctured manifold**  $M^*(x_0, ..., x_k) = M / \cup C(x_i)$ 

•  $dist^2(x, x_i)$ ,  $\log_x(x_i)$  are smooth but  $M^*$  may be split in pieces

Affinely independent points:

 $\{\overrightarrow{x_i x_j}\}_{0 \le i \ne j \le k}$  exist and are linearly independent for all i

# Local well posedness for the barycentric simplex:

- □ EBS / KBS are well defined in a neighborhood of reference points
- For reference points in a sufficiently small ball and positive weights: unique Frechet = Karcher = Exp Barycenter in that ball: smooth graph of a k-dim function [proof using Buser & Karcher 81]

# **SVD characterization of EBS:** $\mathfrak{M}_1(x,\lambda) = Z(x)\lambda = 0$

- $\Box \quad \mathsf{SVD:} \ Z(x) = [\overrightarrow{xx_0}, \dots \overrightarrow{xx_k}] = U(x)S(x)V^t(x)$ 
  - $EBS(x_0, ..., x_k) =$ Zero level-set of l>0 singular values of Z(x)
  - Stratification on the number of vanishing singular values

[X.P. Barycentric Subspace Analysis on Manifolds. Annals of statistics. 2018. To appear. arXiv:1607.02833]

# **Analysis of Barycentric Subspaces**

**Exp. barycenters are critical points of**  $\lambda$ **-variance on M\***  $\Box \nabla \sigma^2(\mathbf{x},\lambda) = -2\mathfrak{M}_1(\mathbf{x},\lambda) = 0$  *KBS*  $\cap M^* \subset EBS$ 

**Caractérisation of local minima: Hessian (if non degenerate)**  $H(\mathbf{x},\lambda) = -2\sum_{i} \lambda_{i} D_{x} \log_{x}(x_{i}) = \mathrm{Id} - \frac{1}{3} \mathrm{Ric}(\mathfrak{M}_{2}(\mathbf{x},\lambda)) + \mathrm{HOT}$ 

Regular and positive pts (non-degenerated critical points)

$$\Box \ EBS^{Reg}(x_0, ..., x_k) = \{ x \in Aff(x_0, ..., x_k), s.t. \ H(x, \lambda^*(x)) \neq 0 \}$$

 $\Box \ EBS^{+}(x_{0}, ..., x_{k}) = \{ x \in Aff(x_{0}, ..., x_{k}), s.t. \ H(x, \lambda^{*}(x)) \ Pos. \ def. \}$ 

Theorem: EBS partitioned into cells by the index of the Hessian of  $\lambda$ -variance: KBS = EBS<sup>+</sup> on M<sup>\*</sup>

[X.P. Barycentric Subspace Analysis on Manifolds. Annals of statistics. 2018. To appear. arXiv:1607.02833]

# **Example on the sphere**



### □ Unit sphere $\mathcal{M} = S_n$ embedded in $\mathbb{R}^{n+1}$ □ $||\mathbf{x}|| = 1$

## Exp and log map

$$\exp_{x} (v) = \cos(||v||) x + \frac{\sin(||v||)}{||v||} v$$
  
$$\log_{x} (y) = f(\theta)(y - \cos(\theta)) \quad \text{with} \quad \theta = \arccos(x^{t}y)$$

ХÝ

**Distance**  $dist(x, y) = ||\log_x(y)|| = \theta$ 

## (k+1)-pointed & punctured Sphere

 $\square \ X = [x_0, x_1, \dots, x_k] \in (S_n)^k$ 

□ Punctured sphere: exclude antipodal points:  $S_n^* = S_n / -X$ 

T<sub>x</sub>M

# KBS / FBS with 3 points on the sphere

**EBS:** great subspheres spanned by reference points (mod cut loci)  $EBS(x_0, ..., x_k) = Span(X) \cap S_n \setminus Cut(X)$   $Aff(x_0, ..., x_k) = Span(X) \cap S_n$ 

#### **KBS/FBS:** look at index of the Hessian of $\lambda$ -variance

 $H(\mathbf{x},\lambda) = \sum \lambda_i \theta_i \cot(\theta_i) (\mathrm{Id} - \mathbf{x}\mathbf{x}^{\mathrm{t}}) + \sum (1 - \lambda_i \theta_i \cot(\theta_i)) \overline{xx_i} \overline{xx_i}^{\mathrm{t}}$ 

Complex algebric geometry problem [Buss & Fillmore, ACM TG 2001]
 3 points of the n-sphere: EBS partitioned in cell complex by index of critical point
 KBS/EBS less interesting than EBS/affine span



Weighed Hessian index: **brown = -2 (min) = KBS** / green = -1 (saddle) / blue = 0 (max)

# Example on the hyperbolic space

#### Manifold

 □ Unit pseudo-sphere M = H<sub>n</sub> embedded in Minkowski space ℝ<sup>1,n</sup>
 □ ||x||<sup>2</sup><sub>\*</sub> = -x<sub>0</sub><sup>2</sup> + x<sub>1</sub><sup>2</sup> + … x<sub>n</sub><sup>2</sup> = -1

## Exp and log map

$$\exp_{x} (v) = \cosh(\|v\|_{*}) x + \frac{\sinh(\|v\|_{*})}{\|v\|_{*}} v$$
  
$$\log_{x} (y) = f_{*}(\theta)(y - \cosh(\theta)) \quad \text{with} \quad \theta = \operatorname{arcosh}(-\langle x|y \rangle_{*})$$

**Distance**  $dist(x, y) = ||\log_x(y)||_* = \theta$ 

#### Punctured hyperbolic space: no cut locus to exclude

# Example on the hyperbolic space

**EBS = Affine span: great sub-hyperboloids spanned by reference points**  $EBS(x_0, ..., x_k) = Aff(x_0, ..., x_k) = Span(X) \cap H_n$ 

#### **KBS:** locus of maximal index of the Hessian of $\lambda$ -variance

 $H(\mathbf{x},\lambda) = \sum \lambda_i \theta_i \coth(J + J \mathbf{x} \mathbf{x}^t J^t) + \sum (1 - \lambda_i \coth(\theta_i)) J \overrightarrow{xx_i} \overrightarrow{xx_i}^t J^t$ 

Complex algebric geometry problem

□ 3 points on H<sup>n</sup>: better than for spheres, but still disconnected components



Weighted Hessian Index: **brown = -2 (min) = KBS** / blue = 1 (saddle)

# Geodesic subspaces are limit cases of affine span

#### Theorem

- $\Box GS(x, w_1, \dots, w_k) = \{ \exp_x(\sum_i \alpha_i w_i) \text{ for } \alpha \in \mathbb{R}^k \} \text{ is the limit} \\ \text{ of } Aff(x_0, \exp_{x_o}(\epsilon w_1), \dots \exp_{x_o}(\epsilon w_k)) \text{ when } \epsilon \to 0.$
- □ Reference points converge to a 1<sup>st</sup> order (k,n)-jet
  - PGA [Fletcher et al. 2004, Sommer et al. 2014]
  - GPGA [Huckemann et al. 2010]

### Conjecture

□ This can be generalized to higher order derivatives

- Quadratic, cubic splines [Vialard, Singh, Niethammer]
- Principle nested spheres [Jung, Dryden, Marron 2012]
- Quotient of Lie group action [Huckemann, Hotz, Munk, 2010]

# **Application in Cardiac motion analysis**



#### [Marc-Michel Rohé et al., MICCAI 2016, MedIA 45:1-12, 2018]

# **Application in Cardiac motion analysis**



- *v<sub>i</sub>* registers image to reference i
- $\sum_i \lambda_i v_i = \mathbf{0}$

Optimize reference images to achieve best registration over the sequence



[Marc-Michel Rohé et al., MICCAI 2016, MedIA 45:1-12, 2018]

# **Application in Cardiac motion analysis**

# **Barycentric coefficients curves Optimal Reference Frames** $\boldsymbol{\lambda} = (0, 1, 0)$ $\lambda_3 < 0$ N $\lambda_2 < 0$ $\lambda = (1, 0, 0)$ $\lambda = (0, 0, 1)$

#### [Marc-Michel Rohé et al., MICCAI 2016, MedIA 45:1-12, 2018]

# **Cardiac Motion Signature**



Dimension reduction from **+10M voxels** to **3 reference** frames + **60 coefficients** Tested on **10 controls** [1] and **16 Tetralogy of Fallot** patients [2]

[1] Tobon-Gomez, C., et al.: Benchmarking framework for myocardial tracking and deformation algorithms: an open access database. Medical Image Analysis (2013)
 [2] Mcleod K., et al.: Spatio-Temporal Tensor Decomposition of a Polyaffine Motion Model for a Better Analysis of Pathological Left Ventricular Dynamics. IEEE TMI (2015)

# **Cardiac motion synthesis**

#### **Original Sequence**

#### **Barycentric Reconstruction**

#### (3 images)

PCA Reconstruction

(2 modes)



#### 30 images

#### 3 images + 2 coeff.

1 image + 2 SVF + 2 coeff.

Reconstr. error: 18.75 Compression ratio: 1/10 Reconstr. error: 26.32 (+40%) Compression ratio: 1/4

[Marc-Michel Rohé et al., MICCAI 2016, MedIA 45:1-12, 2018]

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# Forward, Backward and Nested Analysis

#### Forward Barycentric Subspace (k-FBS) decomposition

- □ Iteratively add points  $x_j$  from j=0 to k
- $\square$   $x_0 = Mean(y_j), \quad x_1 = argmin_x(\sigma_{out}^2(x_0, x)) \dots$  PGA-like
- □ Start with 2 points:  $(x_0, x_1) = \operatorname{argmin}_{(x,y)}(\sigma_{out}^2(x, y))$  GPGA-like

# **Backward analysis: Pure Barycentric Subspace (k-PBS)**

□ Find  $Aff(x_0, ..., x_k)$  minimizing the unexplained variance:

$$\sigma_{out}^2(x_0, \dots x_k) = \sum_j dist^2(y_j, Proj_{Aff(x_0\dots x_k)}(y_j))$$

- □ Iteratively remove one point from  $(x_0, ..., x_j)$  from j=0 to k
- One optimization only for k+1 points and discrete backward reordering

### From greedy to global optimization?

- $\hfill\square$  Optimal unexplained variance  $\rightarrow$  non nested subspaces
- $\hfill\square$  Nested forward / backward procedures  $\rightarrow$  not optimal
- □ Optimize first, decide dimension later → Nestedness required
   [Principal nested relations: Damon, Marron, JMIV 2014]

# **Barycentric Subspace Analysis (k-BSA)**

#### The natural object for PCA: Flags of subspaces in manifolds

 $\Box x_0 \prec x_1 \prec \cdots \prec x_k$  are k +1 n distinct ordered points of M.

 $\Box FL(x_0 \prec x_1 \prec \cdots \prec x_k)$  is the sequence of properly nested subspaces  $FL_{i(x_0 \prec x_1 \prec \cdots \prec x_k)} = Aff(x_0, \dots, x_i)$  $Aff(x_0) = \{x_0\} \subset \dots Aff(x_0, \dots x_k) \dots \subset Aff(x_0, \dots x_n) = M$  $\sigma_{out}^2(x_0) \ge \dots \ge \sigma_{out}^2(x_0, \dots x_k) \ge \dots \ge \sigma_{out}^2(x_0, \dots x_n) = 0$ 



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# Barycentric Subspace Analysis (k-BSA)

#### Accumulated unexplained variance (area under the curve)

 $\square$  k-BSA optimizes:  $AUV(k) = \sum_{i=0}^{k} \sigma_{out}^2(x_0, ..., x_i)$ 

□ In a Euclidean space with Gaussian  $N(x_0, \Sigma = diag(\sigma_1^2, ..., \sigma_n^2))$ 

 $\sigma_{out}^2(x_0, \dots x_i) = \sigma_{i+1}^2 + \dots \sigma_n^2 \xrightarrow{\rightarrow} AUV(k) = \sum_{i=0}^k i \sigma_i^2 + (k+1) \sum_{i=k+1}^n \sigma_i^2$ 

→ minimal for ordered eigenmodes of  $\Sigma$  with  $\sigma_1 \ge \sigma_2$  ...  $\ge \sigma_n$ 

#### [Barycentric Subspace Analysis on Manifolds, Annals of Statistics 2018]





# Sample-limited barycentric subspace inference

# **Restrict the inference to data points only**

- □ Fréchet mean / template [Lepore et al 2008]
- □ First geodesic mode [Feragen et al. 2013, Zhai et al 2016]
- □ Higher orders: challenging with PGA... but not with BSA



- FBS: Forward Barycentric Subspace
- k-PBS: Pure Barycentric Subspace with backward ordering
- k-BSA: Barycentric Subspace Analysis up to order k

# **Robustness with L<sub>p</sub> norms**

#### Affine spans is stable to p-norms

$$\Box \sigma^p(\mathbf{x}, \lambda) = \frac{1}{p} \sum \lambda_i dist^p(x, x_i) / \sum \lambda_i$$

□ Critical points of  $\sigma^p(\mathbf{x},\lambda)$  are also critical points of  $\sigma^2(\mathbf{x},\lambda')$  with  $\lambda'_i = \lambda_i \operatorname{dist}^{p-2}(x,x_i)$  (non-linear reparameterization of affine span)

## **Unexplained p-variance of residuals**

- □ 2 : more weight on the tail,at the limit: penalizes the maximal distance to subspace
- $\Box$  0 < p < 2: less weight on the tail of the residual errors: statistically robust estimation
  - Non-convex for p<1 even in Euclidean space
  - But sample-limited algorithms do not need gradient information

# **Experiments on the sphere**

#### 3 clusters on a 5D sphere

 10, 9 and 8 points (stddev 6 deg) around three orthogonal axes plus 30 points uniformly samples on 5D sphere



- FBS: Forward Barycentric Subspace: mean and median not in clusters
- 1-PBS / 2-PBS: Pure Barycentric Subspace with backward ordering: ok for k=2 only
- 1-BSA / 2-BSA: Barycentric Subspace Analysis up to order k: less sensitive to p & k

# **Experiments on the hyperbolic space**

# 3 clusters on a 5D hyperboloid (50% outliers)

 15 random points (stddev 0.015) around an equilateral triangle of length 1.57 plus 15 points of stddev 1.0 (truncated at max 1.5)



- FBS: Forward Barycentric Subspace: ok for  $p \leq 0.5$
- 1-PBS / 2-PBS: Pure Barycentric Subspace with backward ordering: ok for k=2 only
- 1-BSA / 2-BSA: Barycentric Subspace Analysis up to order k: ok for  $p \leq 1$

# Take home messages

#### Natural subspaces in manifolds

- PGA & Godesic subspaces:
   look at data points from the (unique) mean
- Barycentric subspaces:
   « triangulate » several reference points
  - Justification of multi-atlases?

# Critical points (affine span) rather than minima (FBS/KBS)

- Barycentric coordinates need not be positive (convexity is a problem)
- □ Affine notion (more general than metric)
  - Generalization to Lie groups (SVFs)?

#### Natural flag structure for PCA

Hierarchically embedded approximation
 subspaces to summarize / describe data



A. Manesson-Mallet. La géométrie Pratique, 1702

# **Open research avenues**

### **Other iterative least squares methods?**

- □ ICA, PLS
- $\square$  Manifold learning  $\rightarrow$  Submanifold learning

# Modulate BSA to account for within subspace distribution

- Gaussian: central points
- Clusters: mixtures of modes
- Extremal references: archetypal analysis

## And applications

- Multi-atlases (brains, heart motion image sequences)
- □ SPD matrices (BCI)

# **Pushing the frontiers of Geometric Statistics**

#### Beyond the mean and unimodal concentrated laws

- □ Flags (nested sequences) of subspace in manifolds
- □ Non Gaussian statistical models within subspaces?

## **Beyond the Riemannian / metric structure**

- □ Riemannian manifolds, Non-Positively Curved (NPC) metric spaces
- Towards Affine connection, Quotient, Stratified spaces

## **Unify statistical estimation theory**

 Explore influence of curvature, singularities (borders, corners, stratifications) on non-asymptotic estimation theory



# **Quotient spaces**

#### Functions/Images modulo time/space parameterization

Amplitude and phase discrimination problem



# Noise in top space = Bias in quotient spaces

The curvature of the **template shape's orbit and presence of noise** creates a repulsive bias



Theorem [Miolane et al. (2016)]: Bias of estimator  $\hat{T}$  of the template TBias $(\hat{T}, T) = \frac{\sigma^2}{2}H(T) + O(\sigma^4)$ where H(T): mean curvature vector of template's orbit

Extension to Hilbert of  $\infty$ -dim: bias for  $\sigma > 0$ , asymptotic for  $\sigma \to \infty$ , [Devilliers, Allasonnière, Trouvé and XP. SIIMS 2017, Entropy, 2017]

#### → Estimated atlas is topologically more complex than should be

# Towards non-smooth spaces

## **Stratified spaces**

- Correlation matrices
  - Positive semi definite (PSD) matrices with unit diagonal [Grubisic and Pietersz, 2004]

# Orthant spaces (phylogenetic trees)

• BHV tree space [Billera Holmes Voigt, Adv Appl Math, 2001] [Nye AOS 2011] [Feragen 2013] [Barden & Le, 2017]



Adapted from [Rousseeuw and Molenberghs, 1994].



Adapted from [Dinh et al, AoS 2018,

# **Can we explain non standard statistical results?**

□ Sticky mean [Hotz et al 2013] [Barden & Le 2017], repulsive mean [Miolane 2017]

□ Faster convergence rate with #sample in NPC spaces [Basrak, 2010]



[Ellingson et al, Topics in Nonparametric Statistics, 2014]

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