

Imagerie Médicale : Principes Physiques, traitement Numérique et Applications Avancées

Ecole Centrale Paris (Option Math. App) -
Mastère Recherche MVA - Mastère IDB – 2007/2008

X. Pennec

Tensor computing & Computational Anatomy



Asclepios team
2004, route des Lucioles B.P. 93
06902 Sophia Antipolis Cedex

<http://www-sop.inria.fr/asclepios>

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Cours 2^e module

Lundi 14 janvier 2008: Delingette (Rappels 1^{er} module et classification)

Lundi 21 janvier 2008: Pennec (Recalage paramétrique géométrique)

Lundi 28 janvier 2008: Pennec (Recalage non rigide iconique)

Lundi 18 février 2008: Pennec (Tenseurs & anatomie algorithmique)

Lundi 25 février 2008: Delingette (Modèles biomécaniques)

Lundi 3 mars 2008: Pennec /Delingette (Quizz et présentation d'articles)

Lundi 10 mars 2008: Pennec/Delingette (Quizz et présentation d'articles)

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Content

Recalage iconique et déformable (rappel)

Imagerie du tenseur de diffusion

Tensor Computing

Computational Anatomy

Conclusion

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Méthodes iconiques : minimisation d'énergie

Critère de similarité + régularisation

$$E(T) = E_{sim}(I, J(T)) + \lambda E_{reg}(T)$$

E_{sim} : Mesure la ressemblance des intensités entre voxels homologues;

E_{reg} : Energie de déformation destinée à régulariser le problème
(Thikhonov, modèles d'élasticité linéaire, mécanique des fluides, etc.).
Bajcsy, Christensen-Miller, Bro-Nielsen, Thirion, Pennec, Cachier, Hellier,
Younes, Trounev, Hermosillo....

□ $E_{reg} = 0$ pour rigide à affine

Pondération intensité / déformation !

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Optimal Criterion for Intensity Similarity

Identity: Sum of Square Differences

$$ssd^2 = \sum_k (I(x_k) - J(T(x_k)))^2$$

Affine: Correlation Coefficient

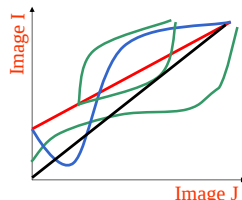
$$\rho^2 = \frac{Cov^2(I, J(T))}{Var(I)}$$

Functional: Correlation Ratio

$$\eta^2 = 1 - \frac{Var(E(I / J(T)))}{Var(I)}$$

Statistical: Mutual Information

$$MI(I, J) = H(I) + H(J) - H(I, J)$$



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PASHA Algorithm

$$E(C, U) = E_s(I, J, C) + \sigma \int \|C - U\|^2 + \lambda \int \|\nabla U\|^2$$

Adding the correspondences as auxiliary variables:

□ Minimization on **C** by differentiation of the similarity criterion
(gradient descent, 1st or 2nd order)

□ Minimization on **U**, explicit solution by Gaussian convolution

P. Cachier E. Bardinet, E. Dormont, X. Pennec and N. A.: *Iconic Feature Based Nonrigid Registration: the PASHA Algorithm*, Comp. Vision and Image Understanding (CVIU), Special Issue on Non Rigid Registration, 89 (2-3), 272-298, 2003.

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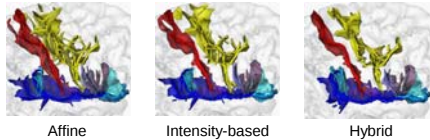
Inter-subject hybrid non-linear registration

PASHA [P. Cathier PhD 2002]

- Demons as an efficient alternated optimization scheme

$$E(C, T) = \text{SIM}(I, J, C) + \frac{1}{\sigma^2} \text{dist}(C, T)^2 + \text{Reg}(T)$$

- Hybrid iconic and feature-based criteria



[Cachier et al, MICCAI 2001, CVIU 89(2-3), 2001]

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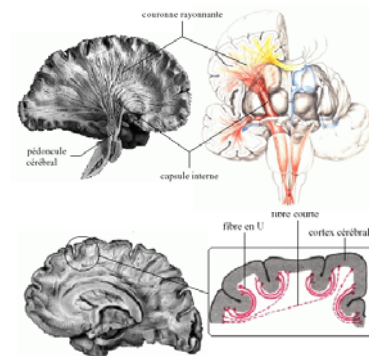
Conclusion

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L'imagerie de diffusion : Introduction

- Technique apparue au milieu des années 80 (Basser, LeBihan).
- IRM classique : image la substance blanche, grise et le liquide céphalorachidien.
- IRM de diffusion : image in vivo l'architecture de la matière blanche.
- Aussi appelée « Imagerie du Tenseur de Diffusion », ou « Diffusion Tensor Imaging » (DTI).

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La substance blanche

- Substance blanche = ensemble de fibres nerveuses (axones).
- Comparable aux câbles d'un réseau : ces liaisons relient les zones de traitement (cortex) entre elles.
- Aussi important à contrôler que les zones de traitement elles-mêmes.
- Le phénomène de diffusion permet d'accéder à cette information.

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Le phénomène de diffusion

- Mouvement Brownien (Einstein) : les molécules dans un milieu s'entrechoquent et changent de direction sans arrêt.
- Phénomène microscopique : mouvement brownien. Phénomène macroscopique : diffusion.
- Si milieu isotrope : la probabilité de déplacement d'une molécule est la même quelque soit la direction.
- Si milieu anisotrope : la probabilité de diffusion/déplacement dépend de la direction de l'espace => tenseur.

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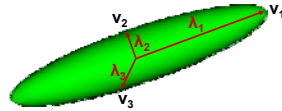
Le Tenseur

Def. mathématique : application multilinéaire (généralisation de l'algèbre linéaire, i.e. des matrices) : On oublie.

Ici : matrices symétriques réelles définies positives.

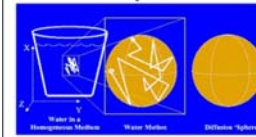
- Réelles def. positive = valeurs propres toutes réelles et >0 .
- Forme quadrique = ellipsoïde.

$$D = \begin{pmatrix} d_{xx} & d_{xy} & d_{xz} \\ d_{xy} & d_{yy} & d_{yz} \\ d_{xz} & d_{yz} & d_{zz} \end{pmatrix}$$



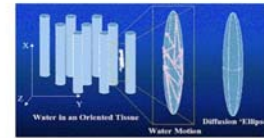
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Isotropic/Anisotropic Diffusion



Isotropic diffusion
($\lambda_1 = \lambda_2 = \lambda_3$)

Anisotropic diffusion
($\lambda_1 > \lambda_2 > \lambda_3$)



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Anatomie d'une séquence IRM de diffusion

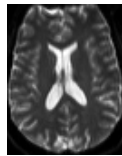
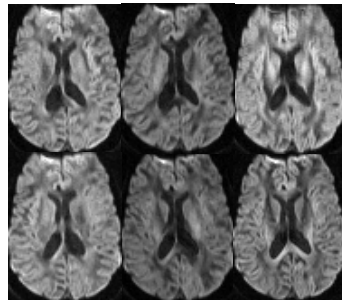


Image T2

+



6 images pondérées en diffusion

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Équation de Stejskal & Tanner

Atténuation du signal reliée au tenseur par :

$$S_i = S_0 \exp(-b \vec{g}_i^T D \vec{g}_i)$$

- S_i : image dite pondérée en diffusion;
- S_0 : image T2;
- $\vec{g}_i$: direction spatiale du gradient de diffusion;
- b : b-value (relié aux paramètres physiques de l'acquisition);
- D : tenseur de diffusion;

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Reconstruction du tenseur de diffusion

- **Tenseur : 6 degrés de liberté.**
 - Au moins 6 images acquises avec 6 gradients non colinéaires.

- **Linéarisation de l'équation de Stejskal & Tanner :**

$$\log\left(\frac{S_0}{S_i}\right) = b \vec{g}_i^T D(x) \vec{g}_i$$

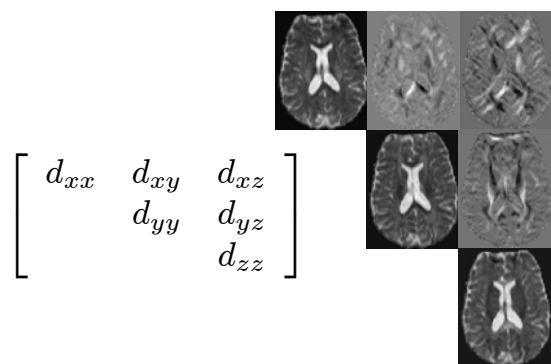
- **Estimation du tenseur aux moindres carrés :**

$$D(x) = \min \sum_{i=1}^N \left(\log\left(\frac{S_0}{S_i}\right) - b \vec{g}_i^T D(x) \vec{g}_i \right)^2$$

- **D'autres méthodes possibles :**
- équations non-linéaires, m-estimateurs.

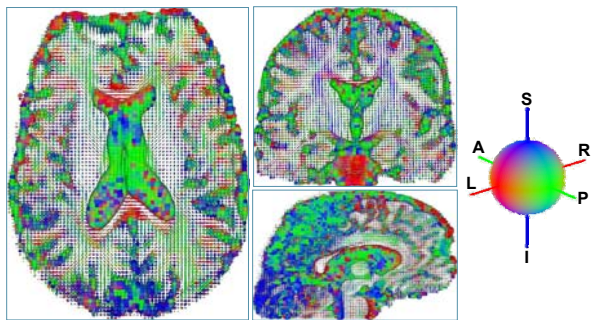
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Coefficients du tenseur



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Visualisation par ellipsoïdes



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Coefficients dérivés du tenseur

- Difficile de visualiser et d'interpréter des images de tenseurs.
- Information riche (direction, amplitude de la diffusion).
- Nécessite de condenser l'information en une image scalaire simple à interpréter pour les cliniciens.

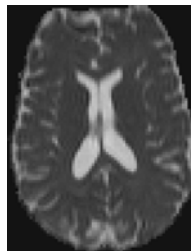
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Le Coefficient de Diffusion Apparente

- Apparent Diffusion Coefficient (ADC) = trace du tenseur :

$$ADC = \text{trace}(D) = \sum_{i=1}^3 \lambda_i$$

- Renseigne sur l'amplitude globale de la diffusion.
- Aucune information sur la direction.



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Les coefficients c_l , c_p et c_s

- Tenseur = somme d'un tenseur sphérique, plat et linéaire :

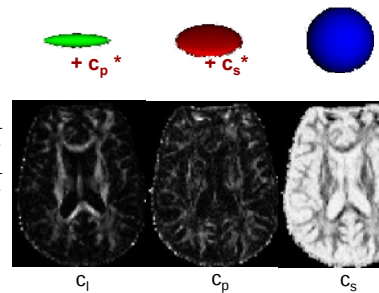
$$D = c_l * \text{[Linear Tensor]} + c_p * \text{[Planar Tensor]} + c_s * \text{[Spherical Tensor]}$$

$$c_s = \frac{3}{\lambda_1 + \lambda_2 + \lambda_3} \lambda_3$$

$$c_p = \frac{2}{\lambda_1 + \lambda_2 + \lambda_3} \lambda_2$$

$$c_l = \frac{\lambda_1 - \lambda_2}{\lambda_1 + \lambda_2 + \lambda_3}$$

$$c_s + c_p + c_l = 1$$



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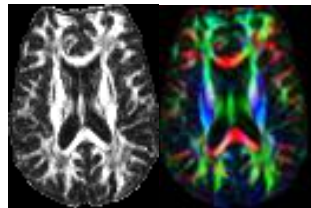
L'Anisotropie fractionnelle

- Fractional Anisotropy (FA) = variance normalisée des valeurs propres (FA entre 0 et 1).

$$FA = \sqrt{\frac{3}{2} \left(\frac{\sum_{i=1}^3 (\lambda_i - \lambda)^2}{\sum_{i=1}^3 \lambda_i^2} \right)}$$

avec $\lambda = \frac{\sum_{i=1}^3 \lambda_i}{3}$

- FA élevée : régions anisotropes = fibres.
- FA = 0 : régions isotropes.



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- Statistical computing on manifolds
- Interpolation, filtering, diffusion PDEs on Tensors
- Other metrics
- Applications in Diffusion tensor imaging

Computational Anatomy

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Diffusion Tensor Imaging

Covariance of the Brownian motion of water
-> Architecture of axonal fibers

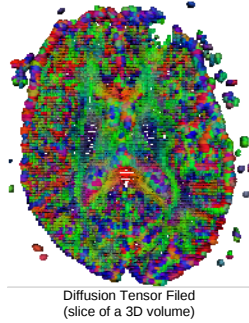
Very noisy data

- Tensor image processing
 - Robust estimation
 - Filtering, regularization
 - Interpolation / extrapolation
- Information extraction (fibers)

Symmetric positive definite matrices

- Convex operations are stable
 - mean, interpolation
- More complex operations are not
 - PDEs, gradient descent...

Intrinsic computing on Manifold-valued images?



Diffusion Tensor Field
(slice of a 3D volume)

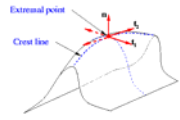
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Probabilités et statistiques simples

Objets géométriques :

- Primitives : points orientés, repères...
- Transformations : rigides, rotations

→ Variétés différentielles



Mesure : vecteur aleatoire x de densité $p_x(z)$

Approximation : $x \sim (\bar{x}, \Sigma_{xx})$

Propagation : $y = h(x) \sim \left(h(\bar{x}), \frac{\partial h}{\partial x} \Sigma_{xx} \frac{\partial h^T}{\partial x} \right)$

Modèle de bruit : additif, gaussien...

Distance statistique : Mahalanobis et χ^2

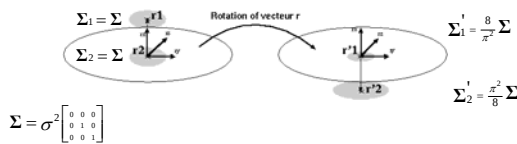
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Quelques problèmes avec la géométrie

Moyenne de rotations 3D : Définition intrinsèque (indep. de la carte)

$$\underline{R} = \frac{1}{n} \sum_i R_i \quad \underline{q} = \frac{1}{n} \sum_i q_i \quad \underline{r} = \frac{1}{n} \sum_i r_i$$

Bruit IID sur les rotations : invariance par un groupe de transfo.



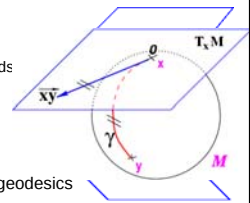
$$\Sigma = \sigma^2 \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

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Riemannian Manifolds: geometrical tools

Riemannian metric :

- Dot product on tangent space
- Speed, length of a curve
- Distance and geodesics
 - Closed form for simple metrics/manifolds
 - Optimization for more complex



Exponential chart (Normal coord. syst.) :

- Development in tangent space along geodesics
- Geodesics = straight lines
- Distance = Euclidean
- Star shape domain limited by the cut-locus
- Covers all the manifold if **geodesically complete**

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Computing on Riemannian manifolds

Operation	Euclidean space	Riemannian manifold
Subtraction	$\vec{xy} = y - x$	$\vec{xy} = \log_x(y)$
Addition	$y = x + \vec{xy}$	$y = \exp_x(\vec{xy})$
Distance	$dist(x, y) = \ y - x\ $	$dist(x, y) = \ \vec{xy}\ _x$
Gradient descent	$\Sigma_{t+\epsilon} = \Sigma_t - \epsilon \nabla Q(\Sigma_t)$	$\Sigma_{t+\epsilon} = \exp_{\Sigma_t}(-\epsilon \nabla Q(\Sigma_t))$

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Computing on manifolds: a summary

The Riemannian metric easily gives

- Intrinsic measure and probability density functions
- Expectation of a function from M into R (variance, entropy)

Integral or sum in M: minimize an intrinsic functional

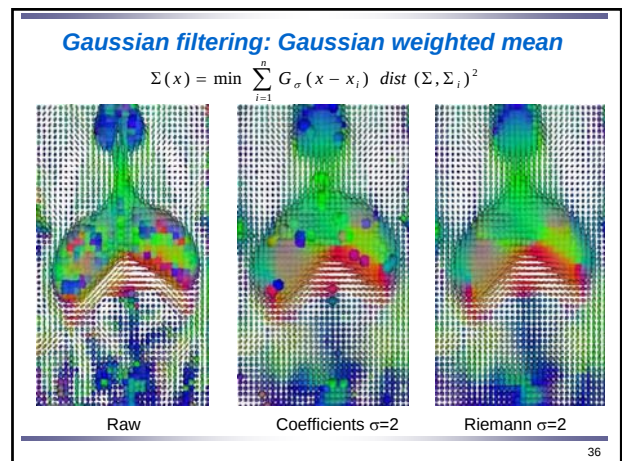
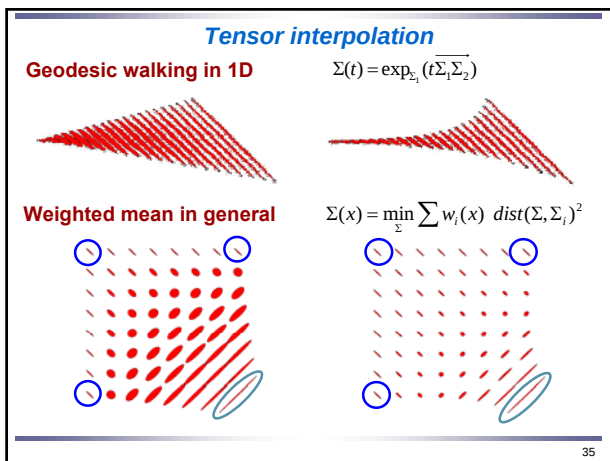
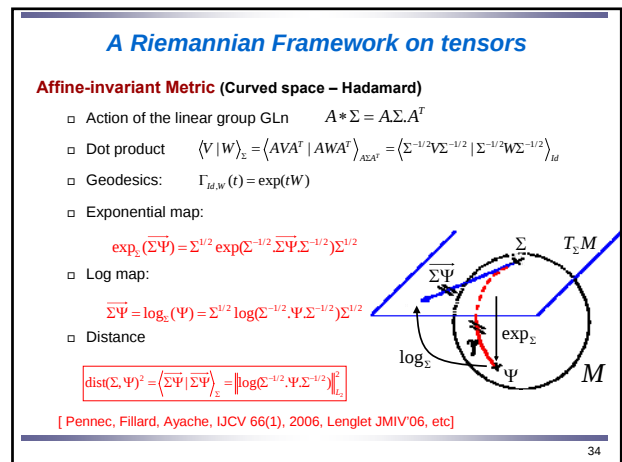
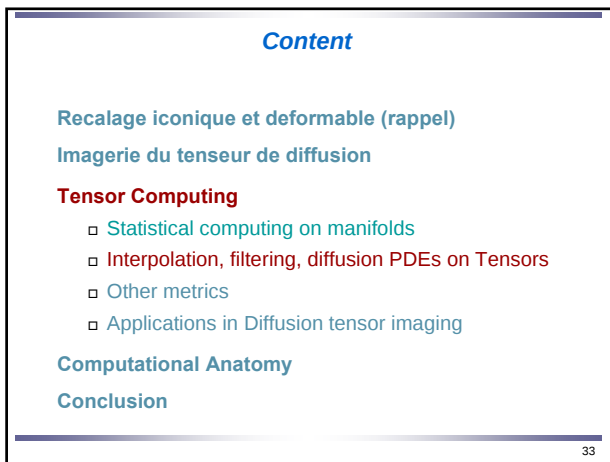
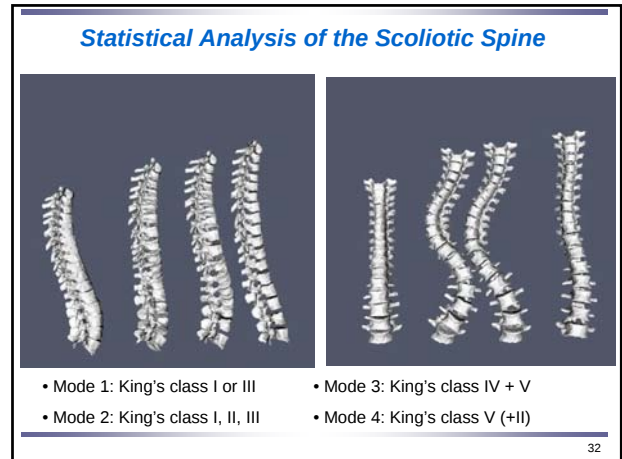
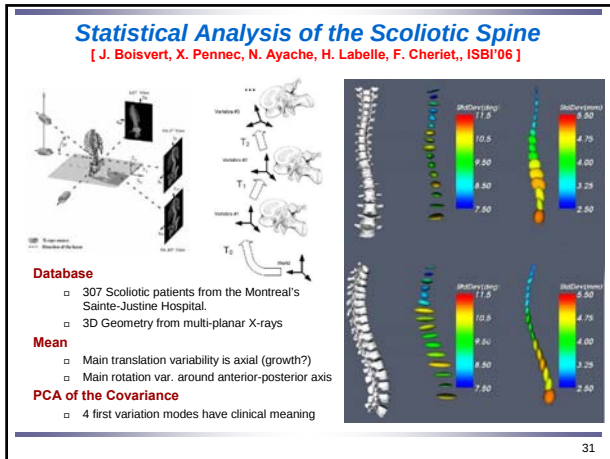
- Fréchet / Karcher mean: minimize the variance
- Filtering, convolution: weighted means
- Gaussian distribution: maximize the conditional entropy

The exponential chart corrects for the curvature at the reference point

- Gradient descent: geodesic walking
- Covariance and higher order moments
- Laplace Beltrami for free

[Pennec, NSIP'99, JMIV 2006, Pennec et al, IJCV 66(1) 2006, Arsigny, PhD 2006]

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PDE for filtering and diffusion

Harmonic regularization

$$C(\Sigma) = \int_{\Omega} \|\nabla \Sigma(x)\|_{\Sigma(x)}^2 dx$$

- Gradient = manifold Laplacian

$$\Delta \Sigma(x) = \sum_i \partial_i^2 \Sigma - \sum_i (\partial_i \Sigma) \Sigma^{(-1)} (\partial_i \Sigma) = \sum_u \frac{\Sigma(x) \Sigma(x+u)}{\|u\|^2} + O(\|u\|^2)$$

- Integration through geodesic marching

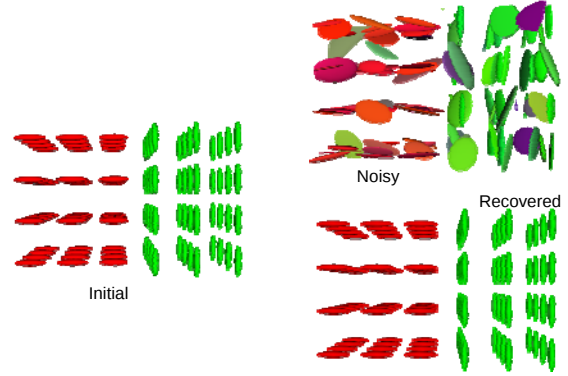
$$\Sigma_{t+1}(x) = \exp_{\Sigma_t(x)}(-\varepsilon \nabla C(\Sigma_t)(x))$$

Anisotropic regularization

- Perona-Malik 90 / Gerig 92
- Phi functions formalism [Odyssee / Deriche]

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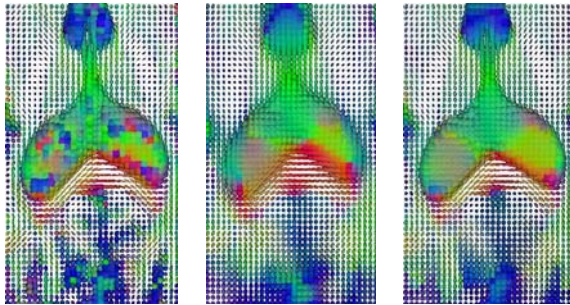
Anisotropic filtering



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Anisotropic filtering

$$\Delta_w \Sigma(x) = \sum_u w(\partial_u \Sigma(x)) \Delta_u \Sigma(x) \quad \text{with} \quad w(t) = \exp(-t^2 / \kappa^2)$$



Raw

Riemann Gaussian

Riemann anisotropic

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Log Euclidean Metric on Tensors

Exp/Log: global diffeomorphism Tensors/sym. matrices

- Vector space structure carried from the tangent space to the manifold

- Log. product $\Sigma_1 \otimes \Sigma_2 = \exp(\log(\Sigma_1) + \log(\Sigma_2))$
- Log scalar product $\alpha \bullet \Sigma = \exp(\alpha \log(\Sigma)) = \Sigma^\alpha$
- Bi-invariant metric $dist(\Sigma_1, \Sigma_2)^2 = \|\log(\Sigma_1) - \log(\Sigma_2)\|^2$

Properties

- Invariance by the action of similarity transformations only
- Very simple algorithmic framework

[Arsigny, Fillard, Pennec, Ayache, MICCAI 2005, T1, p.115-122]

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Riemannian Frameworks on tensors

Affine-invariant Metric (Curved space – Hadamard)

- Dot product $\langle V | W \rangle_{\Sigma} = \langle AVA^T | AWA^T \rangle_{AA^T} = \langle \Sigma^{-1/2} V \Sigma^{-1/2} | \Sigma^{-1/2} W \Sigma^{-1/2} \rangle_{Id}$
- Geodesics $\exp_{\Sigma}(\Sigma \Psi) = \Sigma^{1/2} \exp(\Sigma^{-1/2} \Sigma \Psi \Sigma^{-1/2}) \Sigma^{1/2}$
- Distance $dist(\Sigma, \Psi)^2 = \langle \Sigma \Psi | \Sigma \Psi \rangle_{\Sigma} = \|\log \Sigma^{-1/2} \Psi \Sigma^{-1/2}\|_{Id}^2$

[Pennec, Fillard, Ayache, IJCV 66(1), 2006, Lenglet JMI'06, etc]

Log-Euclidean similarity invariant metric (vector space)

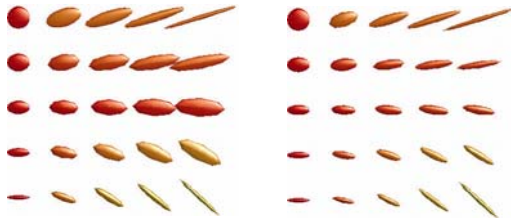
- Transport Euclidean structure through matrix exponential
- Dot product $\langle V | W \rangle_{\Sigma} = \langle \partial_V \log(\Sigma) | \partial_W \log(\Sigma) \rangle_{Id}$
- Geodesics $\exp_{\Sigma}(\Sigma \Psi) = \exp(\log(\Sigma) + \partial_{\Sigma \Psi} \log(\Sigma))$
- Distance $dist(\Sigma_1, \Sigma_2)^2 = \|\log(\Sigma_1) - \log(\Sigma_2)\|^2$

[Arsigny, Pennec, Fillard, Ayache, SIAM'06, MRM'06]

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Log Euclidean vs Affine invariant

- Both means are geometric (vs arithmetic for Euclidean)
- Log Euclidean slightly more anisotropic
- Speedup ratio: 7 (aniso. filtering) to >50 (interp.)



Euclidean

Log-Euclidean

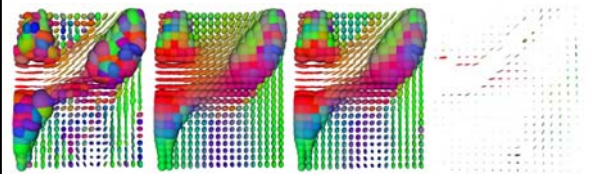
[Arsigny, Fillard, Pennec, Ayache, MICCAI 2005, MRM'06]

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Log Euclidean vs Affine invariant

Real DTI images: anisotropic filtering

- Both means are geometric (vs arithmetic for Euclidean)
- Log Euclidean slightly more anisotropic but the difference is not significant
- Speedup ratio: 7 (aniso. filtering) to >50 (interp.)



Original

Euclidean

Log-Euclidean

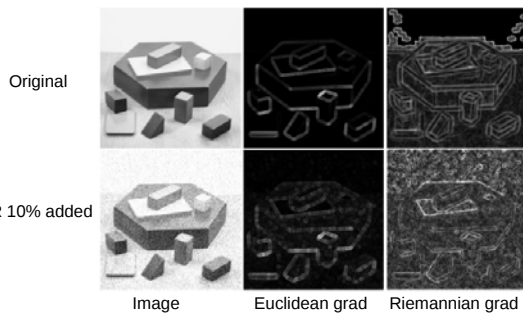
Diff. LE/affine (x100)

[Arsigny, Fillard, Pennec, Ayache, MICCAI 2005, MRM'06]

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Regularization of the Structure Tensor

Structure tensor (guide for diffusion) $\Sigma_{\sigma}(x) = G_{\sigma} * (\nabla I \nabla I^t)$



Original

SNR 10% added

Image

Euclidean grad

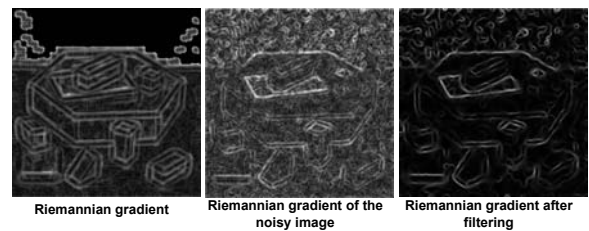
Riemannian grad

[Fillard, Arsigny, Ayache, Pennec, DSSCV'05]

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Regularization of the Structure Tensor

Anisotropic diffusion of the Euclidean grad is unstable!



Riemannian gradient

Riemannian gradient of the noisy image

Riemannian gradient after filtering

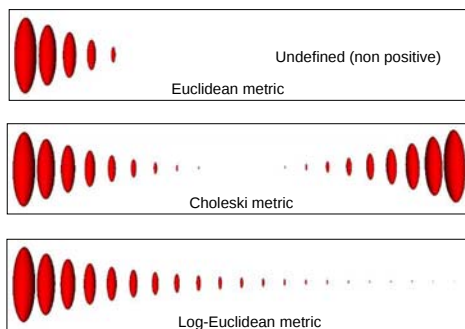
Filtering parameters: $\kappa=0.02$, $dt=0.1$, 500 iterations.

But Riemannian anisotropic diffusion preserve small noise

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Geodesic shooting in tensors spaces

A null eigenvalue is physically plausible: it is a perfect straight edge
Need to change the metric?



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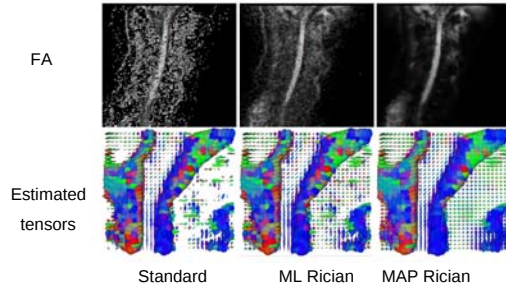
Conclusion

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ML and MAP estimation from DWI with Rician noise

$$C(\Sigma) = \int \sum_i (S_i - S_0 \exp(-b \mathbf{g}_i^T \Sigma(x) \mathbf{g}_i))^2 + \Phi(\|\nabla \Sigma(x)\|_{\Sigma(x)}^2)$$

Clinical DTI of the spinal cord

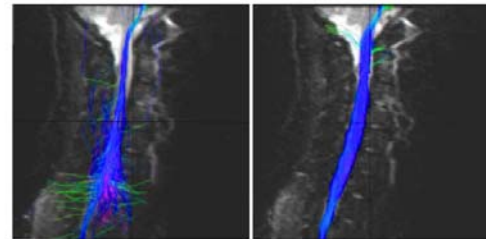


[Fillard, Arsigny, Pennec, Ayache, ISBI 2005]

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Joint Estimation and regularization from DWI

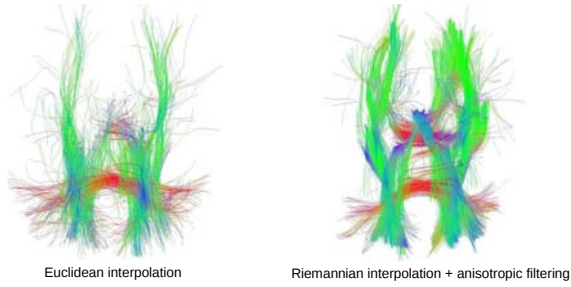
Clinical DTI of the spinal cord: fiber tracking



[Fillard, Arsigny, Pennec, Ayache, ISBI 2005]

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Impact on fibers tracking



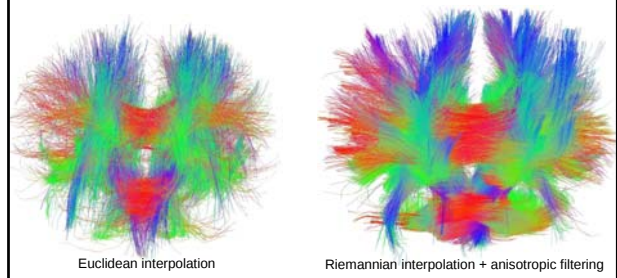
[Fillard, Toussaint et al, MedINRIA: DTI Processing and Visualization Software, 2006]

From images to anatomy

- Classify fibers into tracts (anatomy-functional architecture)?
- Compare fiber tracts between subjects?

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Impact on fibers tracking



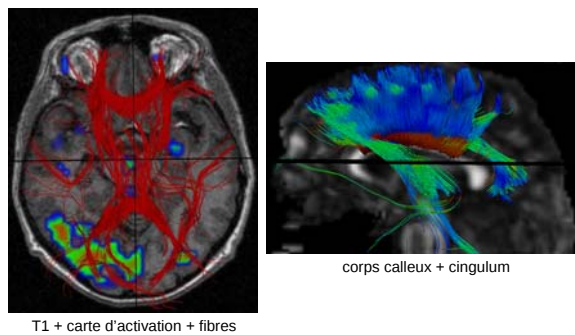
[Fillard, Toussaint et al, MedINRIA: DTI Processing and Visualization Software, 2006]

From images to anatomy

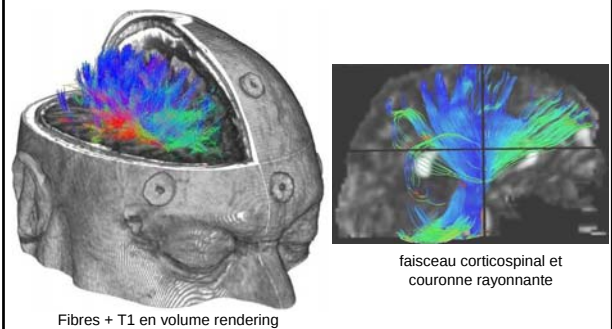
- Classify fibers into tracts (anatomy-functional architecture)?
- Compare fiber tracts between subjects?

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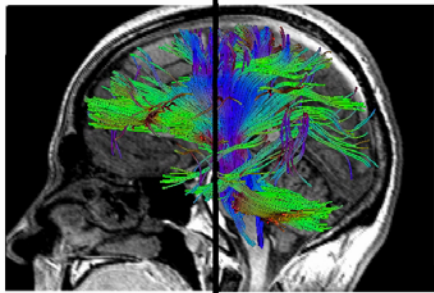
Quelques résultats



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Towards a Statistical Atlas of Cardiac Fiber Structure

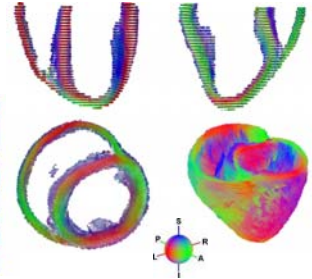
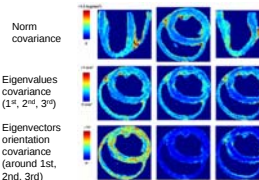
[J.M. Peyrat, et al., MICCAI'06, TMI 26(11), 2007]

Database

- 7 canine hearts from JHU
- Anatomical MRI and DTI

Method

- Normalization based on aMRIs
- Log-Euclidean statistics of Tensors



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Content

Recalage iconique et deformable (rappel)

Imagerie du tenseur de diffusion

Tensor Computing

Computational Anatomy

- Morphometry of sulcal lines on the brain
- Statistics of deformations for non-linear registration

Conclusion

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Anatomy

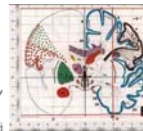
Science that studies the structure and the relationship in space of different organs and tissues in living systems [Hachette Dictionary]



1er cerebral atlas, Vesale, 1543



Pare, 1585



Talairech & Tournoux, 1988



Visible Human Project, NLM, 1996-2000
Voxel Man, U. Hohenberg, 2001

Antiquity
• Animal models
• Philosophical physiology

Renaissance:
• Dissection, surgery
• Descriptive anatomy

17-20e century:
• Anatomico-physiology
• Microscopy, histology

1990-2000:
• Explosion of imaging
• Computer atlases
• Brain decade

Galen (131-201)

Vesale (1514-1564)
Pare (1509-1590)

Sylvius (1614-1672)
Willis (1621-1675)

Gall (1758-1828) : Phrenology
Talairech (1911-2007)

Revolution of observation means (1988-2007) :

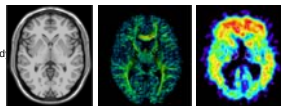
- From dissection to in-vivo in-situ imaging

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The revolution of medical imaging

In vivo observation of living systems

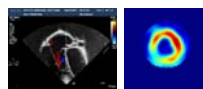
- A large number of modalities to image anatomy and function
 - Growing spatial resolution (molecules to whole body)
 - Multiple temporal scales



brain

Non invasive observations

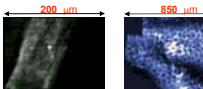
- Emergence of large databases
- From representative individual to population



heart

Extract and structure information

- 50 to 150 MB for a clinical MRI
- Computer analysis is necessary
- From descriptive atlases to interactive and generative models (simulation)
 - MNI 305 (1993), ICBM 152 (2001), Brain web (1999)
 - Bone Morphing® (Fleute et al, 2001)

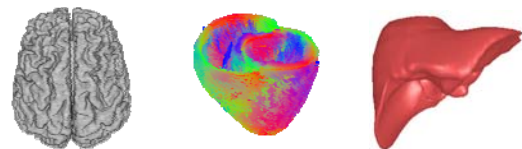


Micro-vaissels

Mouse colon

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Computational Anatomy



Computational Anatomy, an emerging discipline, P. Thompson, M. Miller, NeuroImage special issue 2004
Mathematical Foundations of Computational Anatomy, X. Pennec, S. Joshi, MICCAI workshop, 2006

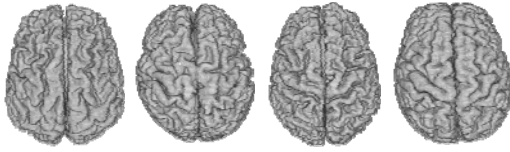
Modeling and Analysis of the Human Anatomy

- Estimate representative / average organ anatomies
- Model organ development across time
- Establish normal variability
- To detect and classify of pathologies from structural deviations
- To adapt generic (atlas-based) to patients-specific models

⇒ Statistical analysis on (and of) manifolds

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Structural variability of the Cortex



Hierarchy of anatomical manifolds

- Landmarks [0D]: AC, PC (Talairach)
- Curves [1D]: crest lines, **sulcal lines**
- Surfaces [2D]: cortex, sulcal ribbons
- Images [3D functions]: VBM
- Transformations: rigid, multi-affine, **diffeomorphisms** [TBM]

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Morphometry of the Cortex from Sulcal Lines

Associated team Brain-Atlas (2001-2006)

- LONI (UCLA) : P. Thompson et al.
- ASCLEPIOS (INRIA): V. Arsigny, N. Ayache, P. Fillard, X. Pennec

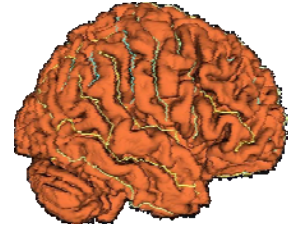
LONI

Neuroanatomical reference:

- 72 sulcal lines manually extracted and labeled
- 700 subjects

Alternative

- Automatic extraction
JF. Mangin, D. Rivière, 2003, SHFJ-CEA



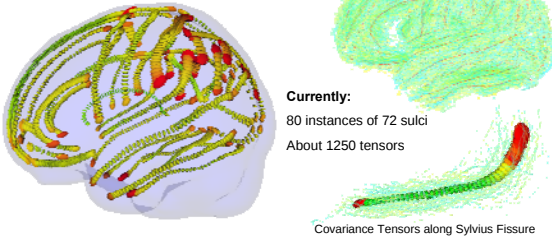
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Morphometry of the Cortex from Sulcal Lines

Computation of the mean sulci: Alternate minimization of global variance

- Dynamic programming to match the mean to instances
- Gradient descent to compute the mean curve position

Extraction of the covariance tensors



Collaborative work between Asclepios (INRIA) and LONI (UCLA) P. Thompson
[Fillard et al IPMI05, LNCS 3565:27-38, NeuroImage 34(2):639-650, January 2007]

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Compressed Tensor Representation



Representative Tensors (250)

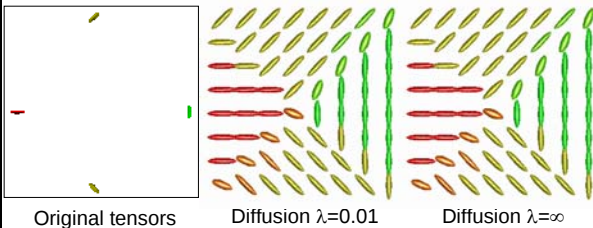
Reconstructed Tensors (1250)
(Riemannian Interpolation)

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Extrapolation by Diffusion

$$C(\Sigma) = \frac{1}{2} \int_{\Omega} \sum_{i=1}^n G_{\sigma}(x - x_i) \text{dist}(\Sigma(x), \Sigma_i)^2 dx + \frac{\lambda}{2} \int_{\Omega} \|\nabla \Sigma(x)\|_{\Sigma(x)}^2$$

$$\nabla C(\Sigma)(x) = - \sum_{i=1}^n G_{\sigma}(x - x_i) \overline{\Sigma(x) \Sigma_i} - \lambda (\Delta \Sigma)(x)$$



Original tensors

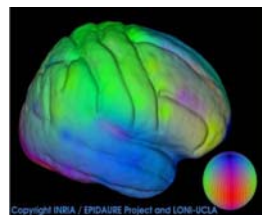
Diffusion $\lambda=0.01$

Diffusion $\lambda=\infty$

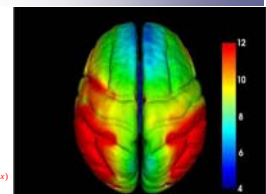
67

Full Brain extrapolation of the variability

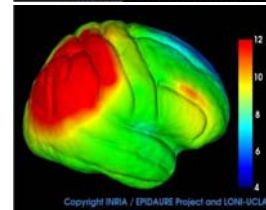
$$C(\Sigma) = \frac{1}{2} \int_{\Omega} \sum_{i=1}^n G_{\sigma}(x - x_i) \text{dist}(\Sigma(x), \Sigma_i)^2 dx + \frac{\lambda}{2} \int_{\Omega} \|\nabla \Sigma(x)\|_{\Sigma(x)}^2$$



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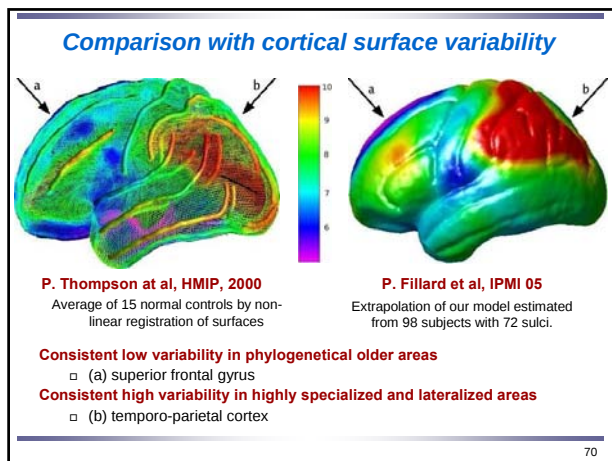


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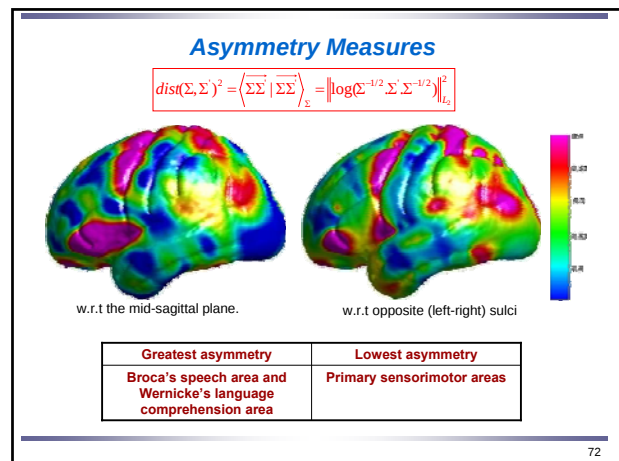


Copyright INRIA / EPIDAURE Project and LONI-UCLA

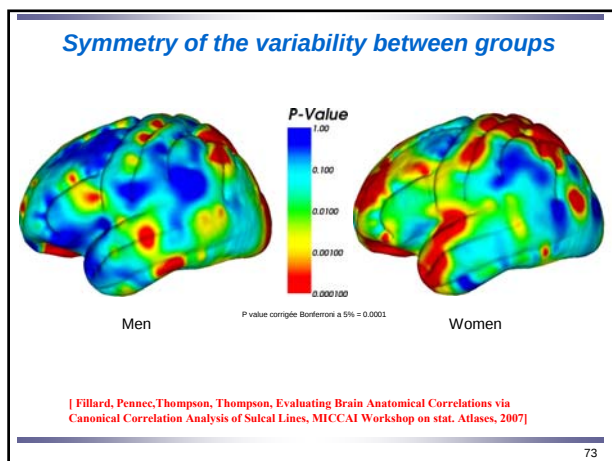
68



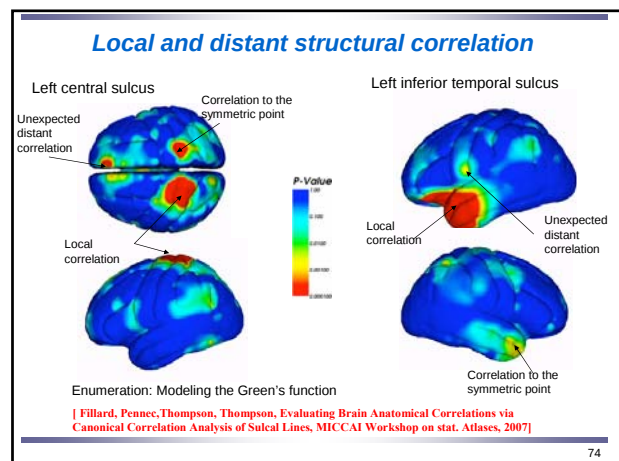
70



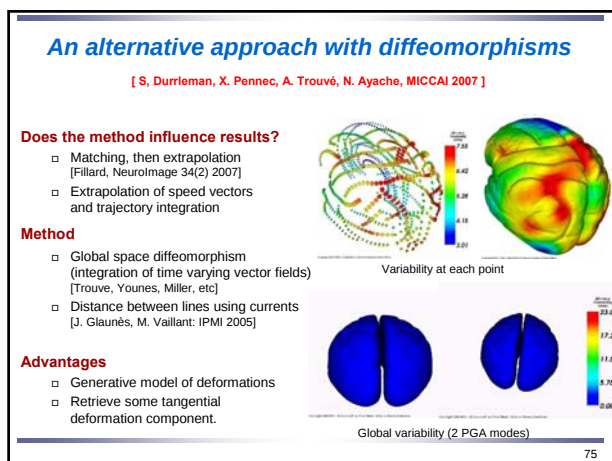
72



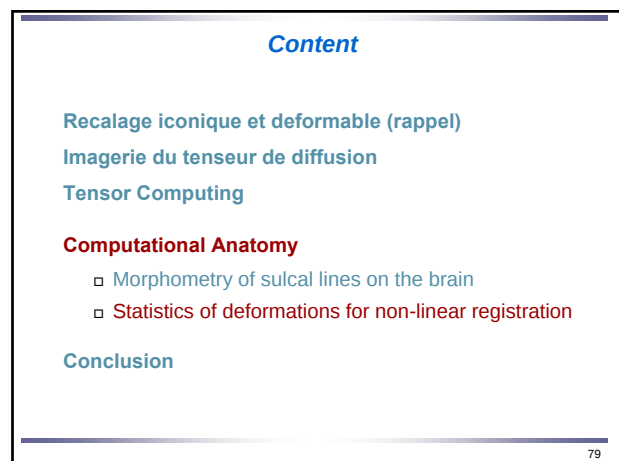
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Use of the variability information?

Learning / modeling phase (anatomy / neurosciences)

- Goal: analyze and understand the population variability
- Fact: Methods have different assumptions
 - Similar results at some locations, different results at other places
 - Each method is based on partial observations
 - Each method is biased by its assumptions
- → **Vary assumptions / data, and discover "truth" by consensus**

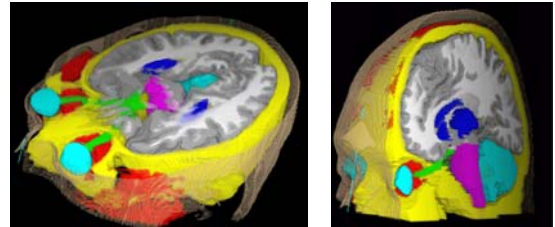
Personalization of atlases (use in a clinical / medical workflow)

- Anatomical prior to compensate for incomplete / noisy / abnormal (pathological) observations.
- **Use variability statistics as a regularizer to robustify registration?**

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One example use of variability information: better constrain the atlas to subject registration

- Deform the atlas anatomy (without tumor) towards the patient one
- Segment the structures of interest in the patient image
- Minimize irradiation in areas at risk.



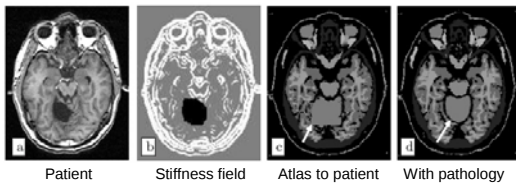
[Commowick, et al, MICCAI 2005]

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Introducing local variability and pathologies in non-linear registration

$$E(T) = E_{sim}(I, J(T)) + \lambda E_{reg}(T)$$

- Non stationary regularization: anatomical prior on the deformability
- Non stationary image similarity / regularization tradeoff: takes pathologies into account



[Runa, Stefanescu et al, PPL 14(2), 2004 & Med. Image Analysis 8(3), 2003]

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Regularization in dense non-linear registration

Physically based regularizations

- Elastic [Bajcsy 89]
- Fluid [Christensen TMI 97]
- Right-invariant distance [LDDMM, Beg IJCV 05]

Efficient regularization methods

- Gaussian filtering [Thirion Media 98, Modersitzki 2004]
- Isotropic but non stationary [Lester IPMI'99]
- Towards anisotropic non stationary regularization [Stefanescu Media 2004]

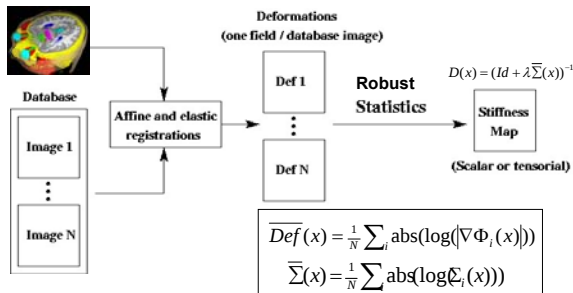
Observation:

- **Inter-subject:** no regularization model is more justified than others
- **Idea:** learning statistically the variability from a population [Thompson 2000, Rueckert TMI 2003, Fillard IPMI 2005]

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Statistics on the deformation field

- Objective: planning of conformal brain radiotherapy (O. Commowick, Dosiof)
- 30 patients, 2 to 5 time points (P-Y Bondiau, MD, CAL, Nice)



[Commowick, et al, MICCAI 2005, T2, p. 927-931]

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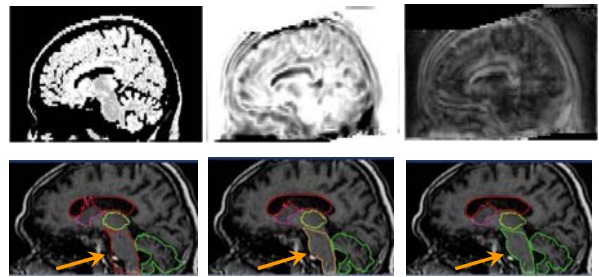
Introducing deformation statistics into RUNA

RUNA [R. Stefanescu et al, Med. Image Analysis 8(3), 2004]

- non linear-registration with non-stationary regularization
- Scalar or tensor stiffness map

$$D(x) = (Id + \lambda \bar{\Sigma}(x))^{-1}$$

Heuristic RUNA stiffness Scalar statistical stiffness Tensor stat. stiffness (FA)



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Riemannian elasticity for Non-linear elastic regularization

Regularization

- Local deformation measure: Cauchy Green strain tensor $\Sigma = \nabla \Phi^T \cdot \nabla \Phi$
 - Id for local rotations, small for local contractions, Large for local expansions
- St Venant Kirchhoff elastic energy $\text{Reg}(\Phi) = \int \mu \text{Tr}((\Sigma - I)^2) + \frac{\lambda}{2} \text{Tr}(\Sigma - I)^2$
 - Elasticity is not symmetric
 - Statistics are not easy to include

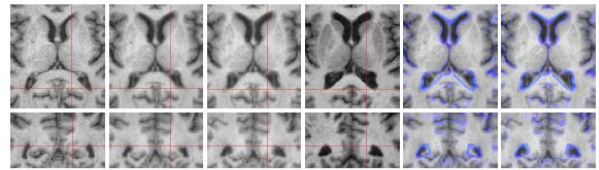
Statistics on the Henky strain tensor: learning the deformation metric

- Idea: Euclidean $\rightarrow$ log-Euclidean $\text{Tr}(\Sigma - I)^2 \rightarrow \text{dist}_{\text{LE}}(\Sigma, I)^2 = \|\log(\Sigma)\|^2$
 - Mean, covariance, Mahalanobis computed in Log-space
- Riemannian Elasticity $\text{Reg}(\Phi) = \int \text{Vec}(\log(\Sigma) - \bar{W})^T \text{Cov}^{-1} \text{Vec}(\log(\Sigma) - \bar{W})$
 - Isotropic case: $\text{Reg}_{\text{iso}}(\Phi) = \int \mu \text{Tr}(\log(\Sigma)^2) + \frac{\lambda}{2} \text{Tr}(\log(\Sigma))^2$
- Locally consistent measure of deformation statistics / regularization criterion

[Pennec, et al, MICCAI 2005]

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Isotropic Riemannian Elasticity Results



Source image Elastic result Riemann res. Target image Elast.+target Riem.+target

Roi 186x124x216 voxels, $\lambda=\mu=0.2$, 12 PC 2Gh.

- Larger computation times 3h vs 1h
- Slightly larger and better deformation of the right ventricle *without any statistical information yet...*

[Pennec, et al, MICCAI 2005, T2, p.943-950]

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Content

Recalage iconique et deformable (rappel)

Imagerie du tenseur de diffusion

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Statistics on geometrical objects

A consistent framework with important applications in

- Medical Image Analysis (registration evaluation, DTI)
- Building models of living systems (spine, brain, heart...)

Is the Riemannian metric the minimal structure?

- No bi-invariant metric but bi-invariant means on Lie groups [V. Arsigny]
- Change the Riemannian metric for the symmetric Cartan connection?

Computational framework for infinite dimensional manifolds

- Curves and surfaces: statistics on currents?
- Efficient framework for some spaces of diffeomorphisms?

How to chose or estimate the metric?

- Invariance, reachability of boundaries, learning the metric
- Families of anatomical deformation metrics (models of the Green's function)

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Challenges of Computational Anatomy

Build models from multiple sources

- Curves, surfaces [cortex, sulcal ribbons]
- Volume variability [Voxel/Tensor Based Morphometry, Riemannian elasticity]
- Diffusion tensor imaging [fibers, tracts, atlas]

Compare and combine statistics on anatomical manifolds

- Each method is biased by its assumptions (fewer data than unknowns)
- Validate methods and models by consensus



Asclepios (INRIA), Visages (IRISA),
Neurospin (CEA + INRIA),
LENA (CNRS-CHUPS),
CMLA (ENS), LSIS (CNRS).

From modeling to personalized medicine

- Topological changes
- Evolution: growth, pathologies
- Couple statistical learning / modeling and use of models as prior for inter-subject registration / segmentation

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Acknowledgements

Image guided therapy

- Brain surgery (Roboscope): A. Roche and P. Cathier
- Dental implantology: S. Granger, AREALL
- Liver puncture guidance: S. Nicolau and L. Soler, IRCAD
- Mosaicing confocal microscopic images: T. Vercauteren, MKT

Brain imaging

- Geometry and statistics for fMRI analysis: G. Flandin, J.-B. Poline, CEA
- Inter-subject non-linear registration: P. Cathier, R. Stefanescu, O. Commowick

Computational anatomy

- Associated team Brain Atlas with LONI: P. Thompson, P. Fillard, V. Arsigny
- Growth and variability: S. Durleman
- Spine shape: J. Boisvert, F. Cheriet, Ste Justine Hospital, Montreal.
- ACI Agir / Grid computing: T. Glatard and J. Montagnat, I3S.

Epidaure / Asclepios Team

- N. Ayache, G. Malandain, H. Delingette
- ... and all the current and former team members.

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