

# Deconvolution in Fluorescence Microscopy-Phase I

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## Problem Statement

- 1 Images of biological specimens obtained from fluorescence microscopes are corrupted by two primary sources:
  - **blurring** due to the band-limited nature of the optical system
  - under low illumination conditions, **noise** due to reduced number of photons reaching the detector.
- 2 Blurring kernel is unknown (**blind deconvolution**).
- 3 Denoising the image can induce artifacts.
- 4 Restoration of the images is **ill-posed**.

# Poisson Statistic for the Image Formation Model

- The statistics for the image formation is described by a **Poisson** process as:

$$i(\mathbf{x}) = \mathcal{P}[h * o](\mathbf{x}) \quad (1)$$

where  $*$  denotes **3D convolution**.

- Likelihood of the observed data  $i$  knowing the specimen  $o$  is given as,

$$P(i|o) = \prod_{\mathbf{x} \in \Omega} \frac{[h * o](\mathbf{x})^{i(\mathbf{x})} e^{-[h * o](\mathbf{x})}}{i(\mathbf{x})!} \quad (2)$$

# Gibbsian distribution with Total Variation (TV)

Gibbsian distribution  $P(X = o)$  with TV functional captures the **prior knowledge** of the object, and is the **regularization model**.

$$P(o) \propto \frac{1}{Z_\lambda} e^{-\lambda \sum_{\mathbf{x} \in \Omega} |\nabla o(\mathbf{x})|}, \quad (3)$$

where,  $|\nabla o(\mathbf{x})| = \left( \sum_{\mathbf{x}' \in V_x} (o(\mathbf{x}) - o(\mathbf{x}'))^2 \right)^{\frac{1}{2}}$ ;  $Z_\lambda = \sum_o e^{-\lambda \sum_{\mathbf{x}} |\nabla o(\mathbf{x})|}$

# Diffraction-limited Point-Spread Function (PSF) model

- For a **fluorescent microscope**,

$$h(\mathbf{x}) = |P_{\lambda_{em}}(\mathbf{x})|^2 \cdot |P_{\lambda_{ex}}(\mathbf{x})|^2 \quad (4)$$

where,  $h$  is the PSF,  $P_{\lambda}(\mathbf{x})$  is the **pupil function** for a wavelength  $\lambda$ .

- If the **pinhole model**  $A_R$  is included, then the analytical CLSM PSF model is,

$$h(\mathbf{x}) = |A_R(\mathbf{x}) * P_{\lambda_{em}}(\mathbf{x})|^2 \cdot |P_{\lambda_{ex}}(\mathbf{x})|^2 \quad (5)$$

# Parametric approach to PSF modeling

- **Assumptions:**
  - 1 Infinitely small pinhole, stationary PSF, ignore aberrations (mirror symmetry about z-axis).
  - 2 Circular symmetry on xy-plane.
- **Diffraction-limited PSF** approximation (in the LSQ sense) [*Zhang et al.* 06]:

$$h_{\sigma_r, \sigma_z}(r, z) = \frac{1}{Z_{\sigma_r, \sigma_z}} e^{\left(\frac{-r^2}{2\sigma_r^2} - \frac{z^2}{2\sigma_z^2}\right)}, \quad (6)$$

$$\text{where, } Z_{\sigma_r, \sigma_z} = (2\pi)^{\frac{3}{2}} \sigma_r^2 \sigma_z$$

## Bayesian model for the restoration

- From the Bayes theorem, the **Posterior probability** is,

$$P(X = o | Y = i) \propto P(Y = i | X = o)P(X = o) \quad (7)$$

- Thus, the **conditional probability** can be written as:

$$P(o|i) \propto \frac{e^{-\lambda \sum_{\mathbf{x} \in \Omega} |\nabla o(\mathbf{x})|}}{\sum_o e^{-\lambda \sum_{\mathbf{x} \in \Omega} |\nabla o(\mathbf{x})|}} \prod_{\mathbf{x} \in \Omega} \frac{[h * o](\mathbf{x})^{i(\mathbf{x})} e^{-[h * o](\mathbf{x})}}{i(\mathbf{x})!} \quad (8)$$

# Alternate Minimization Algorithm

- The **Cost Function** to be minimized has the form:

$$\mathcal{L}(o, h) = -\lambda \sum_{\mathbf{x} \in \Omega} |\nabla o(\mathbf{x})| - \log[Z_\lambda] + \sum_{\mathbf{x} \in \Omega} (i(\mathbf{x}) \log[h * o](\mathbf{x})) - \sum_{\mathbf{x} \in \Omega} [h * o](\mathbf{x}) \quad (9)$$

- Sub-optimal solution **alternatively maximizes** the joint-likelihood in  $o$  and  $h$  to find  $\hat{o}$  and  $h(\hat{\theta})$  [Hebert *et al.* 1989] satisfying :

$$\mathcal{L}(\hat{o}_{new}, h(\hat{\theta}_{new})) \leq \mathcal{L}(\hat{o}_{old}, h(\hat{\theta}_{old})) \quad (10)$$



# Maximum A Posteriori (MAP) estimate of the specimen

- 1 Minimizing the **cost function** (9) w.r.t  $o$ ,

$$\frac{\partial}{\partial o(\mathbf{x})} \mathcal{L}(o(\mathbf{x}) | \lambda, \hat{\theta}) = 0 \quad (11)$$

- 2 **Richardson-Lucy with TV Regularization** [Dey et al. 2004]

$$o_{n+1}(\mathbf{x}) = \left[ \frac{i(\mathbf{x})}{(o_n * h_{\hat{\sigma}_r, \hat{\sigma}_z})(\mathbf{x})} * h_{\hat{\sigma}_r, \hat{\sigma}_z}(-\mathbf{x}) \right] \cdot \frac{o_n(\mathbf{x})}{1 - \lambda \operatorname{div} \left( \frac{\nabla o_n(\mathbf{x})}{|\nabla o_n(\mathbf{x})|} \right)} \quad (12)$$

## PSF parameter estimate

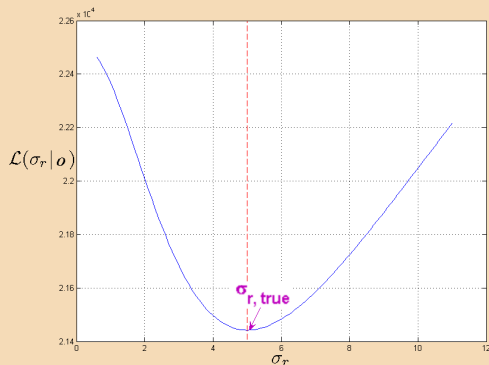
- If we denote  $\theta = (\sigma_r, \sigma_z)$  as the **unknown parameters**, the log-likelihood can be written as:

$$\mathcal{L}(\theta|\hat{o}) = - \sum_{\mathbf{x} \in \Omega} (i(\mathbf{x}) \log[h(\theta) * \hat{o}](\mathbf{x})) + \sum_{\mathbf{x} \in \Omega} [h(\theta) * \hat{o}](\mathbf{x}) \quad (13)$$

- and the gradient w.r.t  $\theta$  as,

$$\nabla_{\theta} \mathcal{L}(\theta) = \sum_{\mathbf{x} \in \Omega} ((h_{\theta_j} * \hat{o}(\mathbf{x})) - \frac{i(\mathbf{x})}{h * \hat{o}(\mathbf{x})} h_{\theta_j} * \hat{o}(\mathbf{x})) \quad (14)$$

## Analysis of Cost Function



Cost Function as a property of the radial PSF parameter when the initial object and observation are known.

## PSF parameter estimate

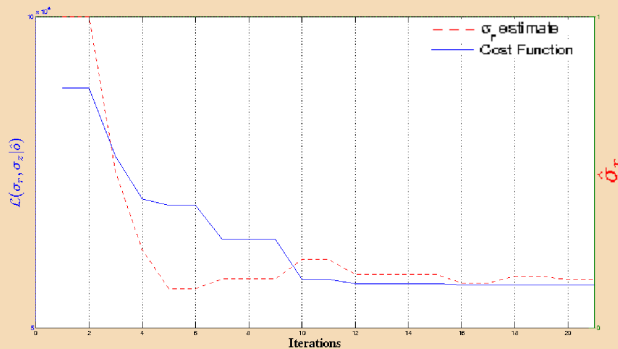
- Conjugate-Gradient algorithm:

$$\hat{\theta}_{k+1} = \hat{\theta}_k - \alpha_k \nabla_{\theta} \mathcal{L}(\hat{\theta}_k | \hat{o}) \quad (15)$$

- Stopping criteria,

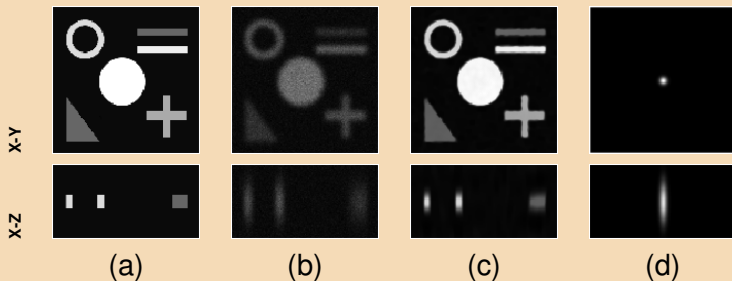
$$\chi_{k+1} = \frac{|\hat{\theta}_{(k+1)} - \hat{\theta}_{(k)}|}{\hat{\theta}_{(k)}} < \epsilon, \quad (\epsilon \leq 10^{-3}) \quad (16)$$

# Analysis on synthetic data



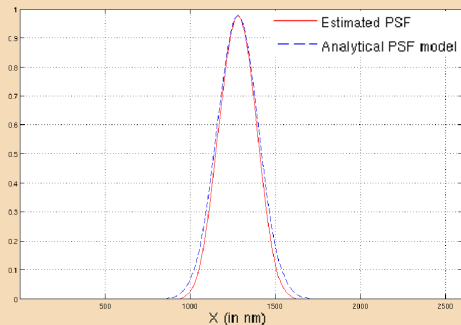
Convergence plot of the radial PSF parameter ( $\sigma_r$ ) by the Conjugate-Gradient method.

## Results on synthetic data



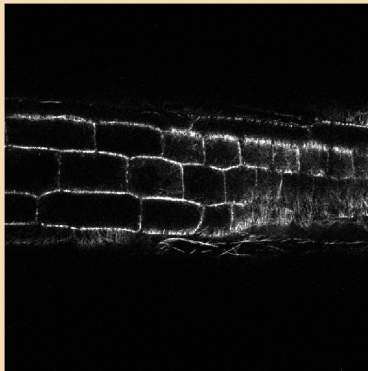
(a) Composite synthetic object, (b) observed image with the analytical blur model and Poisson noise, (c) after RL+TV deconvolution with the estimated PSF, (d) reconstructed diffraction-limited PSF.

## Results on Synthetic Data



Comparison of the analytically and the estimated parametric diffraction-limited PSF models.

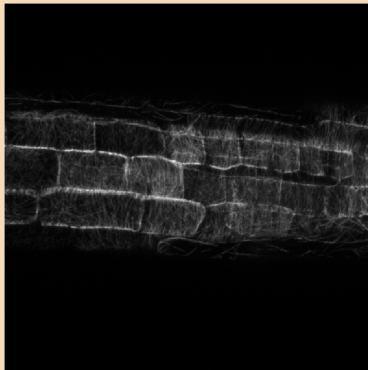
## Preliminary results on real data



Root meristem of the plant *Arabidopsis thaliana* scanned by Zeiss LSM 510, C-Apochromat lens,  $\Delta_{XY}: 0.29\mu m$ ,  
 $\Delta_Z: 0.44\mu m$  (depth of about  $14.08\mu m$ ), ©INRA Sophia-Antipolis



## Preliminary results on real data



Deconvolved Image after restoration by the RL+TV algorithm and PSF parameter estimation

## Conclusions and Future Work

- 😊 The **alternate minimization algorithm** jointly estimates a separable 3D Gaussian PSF and the object.
- 😊 TV regularization **preserves borders** very well.
- 😞 Small structures close to noise are not well restored (staircase effect) and some corners are rounded.
- 😞 Model chosen is for the **diffraction-limited PSF** and does not include spherical aberrations.
  - ▶ Additional experimentation on **confocal image data** of specimens.
  - ▶ Investigate and extend to the **spherically-aberrated PSF** [*Gibson & Lanni, 1991*] or [*P. Török et al., 1995*] and improve the **prior** representation of the specimen.

## References

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- [Dey et.al 04] N. Dey, L. Blanc-Feraud, J. Zerubia, C. Zimmer, J-C. Olivo-Marin and Z. Kam, “A Deconvolution Method for Confocal Microscopy with Total Variation Regularization,” Proc. ISBI'2004, pp.1223-1226, Apr. 2004.

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- [Gibson & Lanni 91] S. F. Gibson and F. Lanni, “*Experimental test of an analytical model of aberrations in an oil-immersion objective lens used in three-dimensional light microscopy*,” Journal of Microscopy, vol. 8, no. 10, pp. 1601-1613, Oct. 1991.
- [Zhang et al 06] B. Zhang, J. Zerubia and J-C. Olivo-Marin, “*A study of Gaussian approximations of fluorescence microscopy PSF models*,” SPIE Conf. on microbiology, San Jose, Jan. 2006.